



Modifying IBIS models

SIEMENS

Overview

- **Motivation**
- **Possible simulation types**
- **considered changes**
 - C_comp
 - $U(i)$: driver strength, clamps
 - $U(t)$, ramp
 - Missing models
- **Conclusion**

Motivation

- **Short time until simulation will start**
- **The quality of delivered models is more than ambiguous**
or
- **No model available**
- **Consideration of available ibis parameter versus datasheet/
technology/ measurement/ experience**
- **Need for a „worst case model“ but what does that mean?**

Types of Simulation

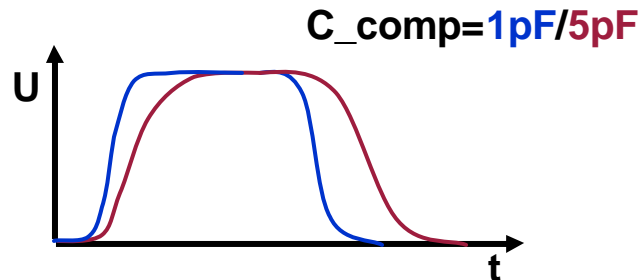
- **Signal Integrity**
 - under/overshoots
- **Timing: setup and hold time of clock net**
- **Crosstalk**
- **EMI**
 - radiation

C_comp @ receiver

$C_{\text{comp}} + C_{\text{pkg}} = \text{Capacitance in Datasheet (min/typ/max)}$

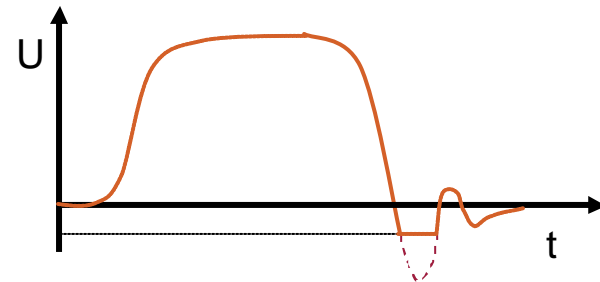
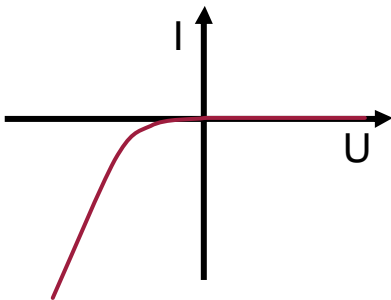
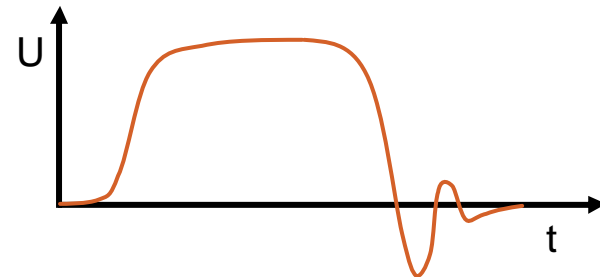
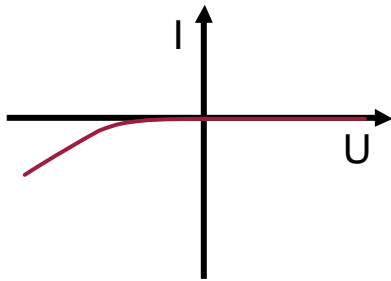
Normally: $C_{\text{comp_IO}} > C_{\text{comp_input}}$

Make C_{comp} smaller \Rightarrow ramp gets faster



Diodes @ receiver

flat gnd-diode => large undershoot
steep gnd-diode => small undershoot



No/wrong PVT-min-max curves -> scaling U(I)

$$I_{\max} = I_{\text{typ}}(1+F)$$

$$I_{\min} = I_{\text{typ}}(1-F)$$

$$F = F_P + F_V + F_T \text{ (independent variables)}$$

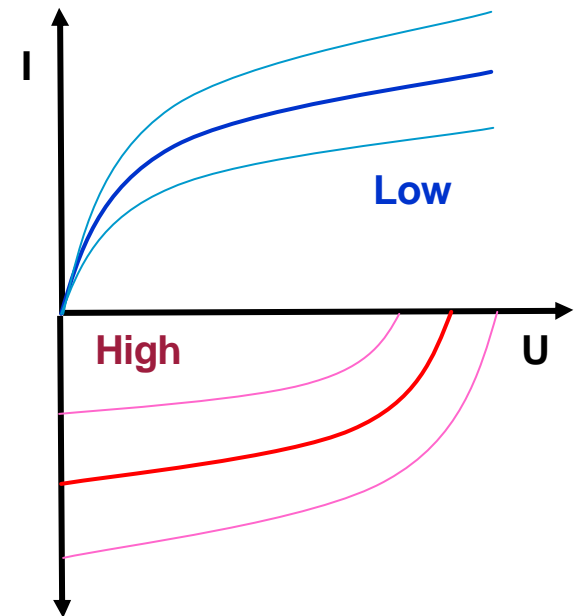
For example CMOS 3.3V:

$$F_{\text{process}} = 0.30 \pm 0.15 \text{ (weak/strong } 3\sigma)$$

$$F_{\text{temperature}} = 0.12 \pm 0.06 \text{ (0,55,100C)}$$

$$F_{\text{vcc}} = 0.08 \pm 0.02 \text{ (vcc} \pm 5\%)$$

would result in $F = 0.50 \pm 0.23$



No/wrong PVT-min-max curves -> scaling U(t)

$$t_{\max} = (1+F) \cdot t_{\text{typ}}$$

$$t_{\min} = (1+F) \cdot t_{\text{typ}}$$

Get $U_{\max/\min}$ out of intersection from $I_{\max/\min}$

$F = F_P + F_V + F_T$ (independent variables)

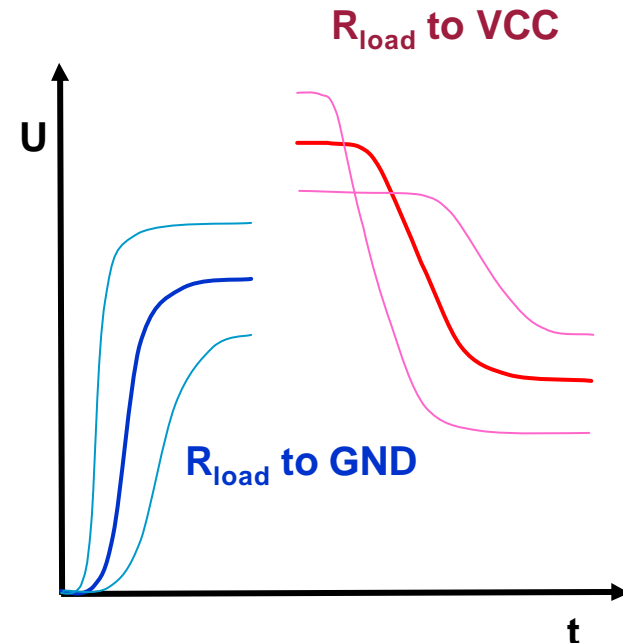
For example CMOS 3.3V:

$$F_{\text{process}} = 0.27 \pm 0.23 \text{ (weak/strong } 3\sigma)$$

$$F_{\text{temperature}} = 0.15 \pm 0.09 \text{ (0,55,100C)}$$

$$F_{\text{vcc}} = 0.03 \pm 0.02 \text{ (vcc } \pm 5\%)$$

would result in **$F = 0.45 \pm 0.34$**



Missing Model: e.g. 4mA Driver

- no 4mA-model from vendor
- We have:
 - 1) model from another vendor, other technology, 4mA
 - 2) model from the same vendor, other technology, 4mA
 - 3) model from the same vendor, similar technology, 4mA
- Copy one model from above

Missing model: e.g. Open_drain

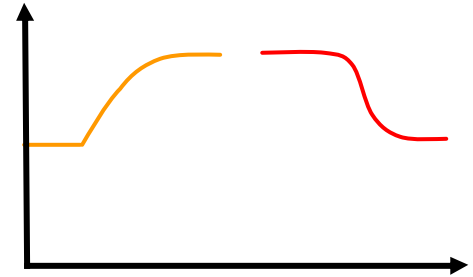
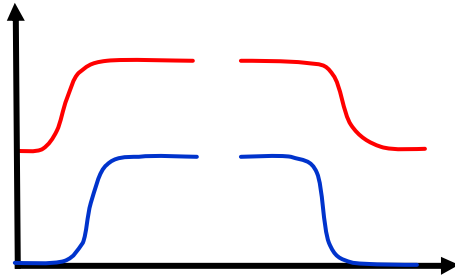
- No OD-model from vendor
- We have:
 - 1) OD-model from another vendor, other technology
 - 2) OD-model from the same vendor, other technology
 - 3) OD-model from the same vendor, similar technology
 - 4) push-pull model available
- conversion of push-pull to open_drain
 - $U(t)$: simulation from 3-state to low
 - $U(I)$: skip pullup curve

Missing model: Open_drain

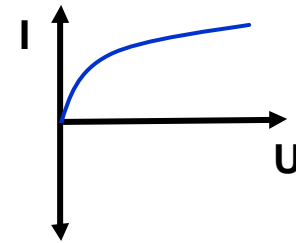
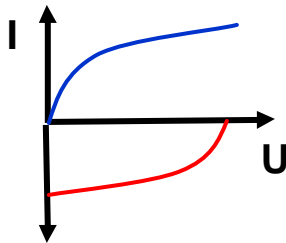
Push-pull

Open_drain

dynamic



static



Discussion of Changes

		Overshoot	t_setup	t_hold	Crosstalk	EMI
C_comp @ REC	large	+	-	+	+	+
	small	-	+	-	-	-
Diodes @ REC	large/steep	+	+	o	+	+
	small/flat	-	-	o	-	-
Driver Strength	large	-	+/-	-	-	-
	small	+	-	+	+	+
Ramp	large/steep	-	+	-	-	-
	small/flat	+	-	+	+	+
Missing Models	nothing	no info				
	default OD	great uncertainty				
	default simulated OD	more realistic				

⊕ = no errors

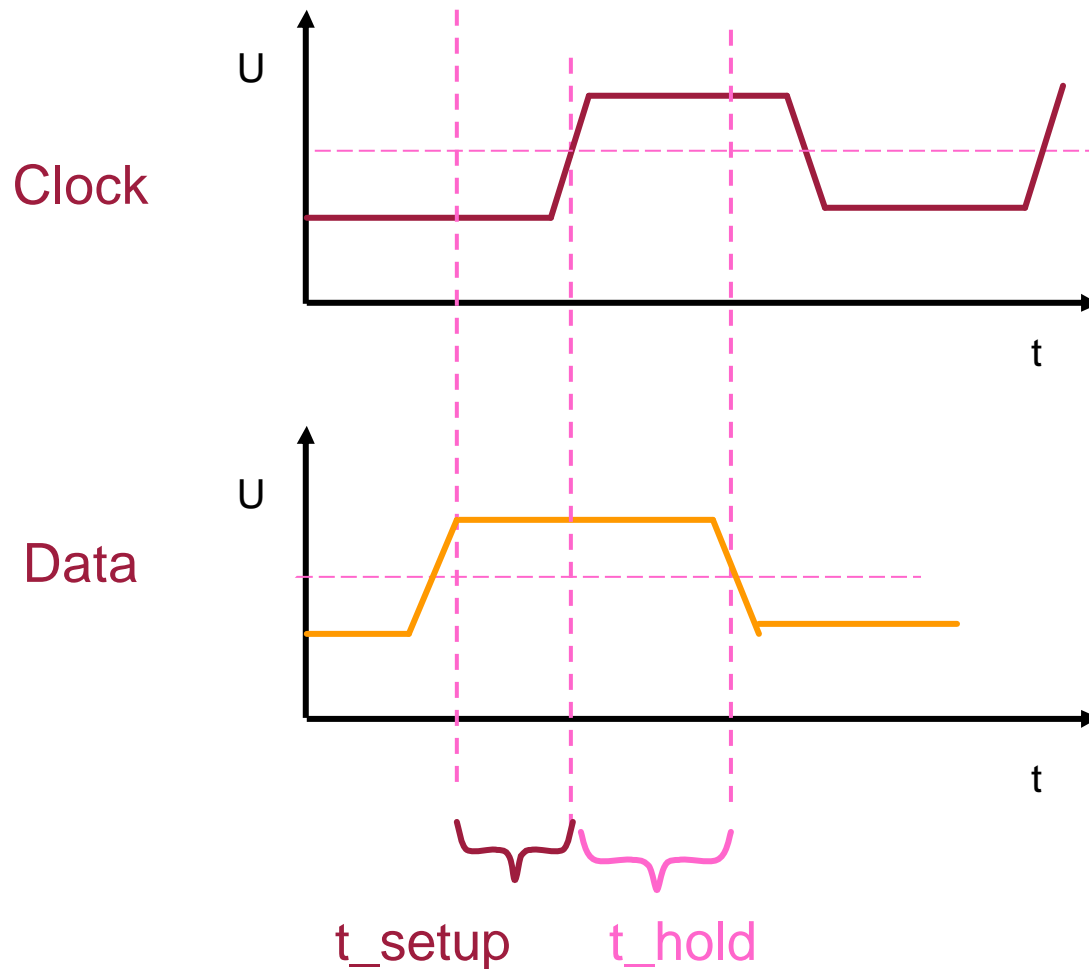
- = errors

o = not relevant

Summary and Conclusion

- **Changing ibis does effect the simulation in a great manner**
- **Changes are in some simulation type more worst case and in an other more best case**
- **Every model „worst case“ → NO system design**
- **More and faster cooperation from vendor is needed**
- **IF necessary, better adjustment of scaling parameters**

Timing: Setup and Hold Time



t_{setup} : the time, the data has to be stable high, until the clk starts rising (stable **before** the CK-edge)

t_{hold} : the time away from the clk goes high, the data has to be stable high (stable **after** the CK-edge)

$t_{\text{setup}} + t_{\text{hold}}$ is the *minimal data pulse width*