

Using the ATV2500 and ATV2500B

Introduction

This application note describes how to use the features of the ATV2500 and ATV2500B in the ABEL (and Atmel-ABEL) and CUPL (and Atmel-CUPL) high level description languages. The ATV2500 and ATV2500B are the most powerful programmable logic devices available in a 40/44-pin package. They combine high density and global routing, making them easy to use and understand. Both devices have 24 macrocells, each with three sum terms, two registers, and 17 product terms. Each register has individual clock and AR product terms. Each I/O pin has a programmable polarity control and an individual output enable product term. Independent feedback paths from each register allow all of the registers to be buried without wasting the I/O pins. A universal bus routes all input and feedback signals to all product terms on all macrocells. The ATV2500B has the additional features of D- or T-type configurable registers, three different clock options, and buried combinatorial nodes. The ATV2500 and ATV2500B macrocell is shown in Figure 1.

Device Names and Pin and Node Assignments

The device names for the ATV2500 and ATV2500B for each language are shown in Table 1.

The buried nodes (Q1 and Q2/F2 in each macrocell) are identified by node numbers, as shown in Table 2.

The following examples show the device type specification and the pin and node assignments:

ABEL and Atmel-ABEL

```
device_id device `P2500B';
  "device_id will be used for
  "JEDEC filename

I1,I2,I3,I17,I18 pin 1,2,3,17,18;
O4,O5 pin 4,5 istype `reg_d,buffer';
O6,O7 pin 6,7 istype `com';
O4Q2,O7Q2 node 41,44 istype `reg_d';
O6F2 node 43 istype `com';
O7Q1 node 220 istype `reg_d';
```

CUPL and Atmel-CUPL

```
device V2500B;
pin [1,2,3,17,18] =
  [I1,I2,I3,I17,I18];
pin [7,6,5,4] = [O7,O6,O5,O4];
pinnode [41,65,44] =
  [O4Q2,O4Q1,O7Q2];
pinnode [43,68] = [O6Q2,O7Q1];
```

Table 1. Device Names

Device Type	ABEL Device Name	CUPL Device Name
ATV2500 DIP	P2500	V2500
ATV2500 PLCC	P2500C	V2500LCC
ATV2500B DIP	P2500B	V2500B
ATV2500B PLCC	P2500BC	V2500BLCC

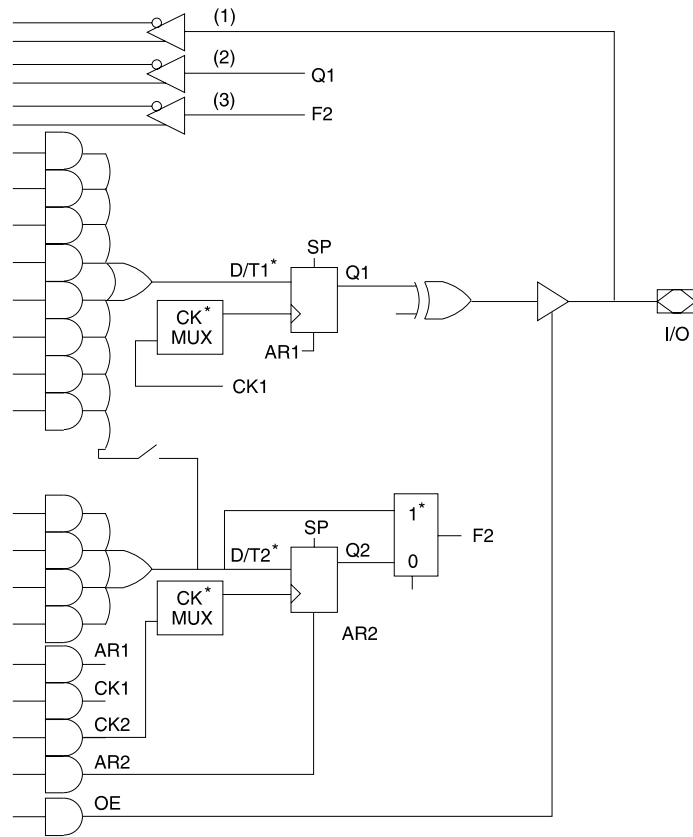
Erasable Programmable Logic Device

Application Note

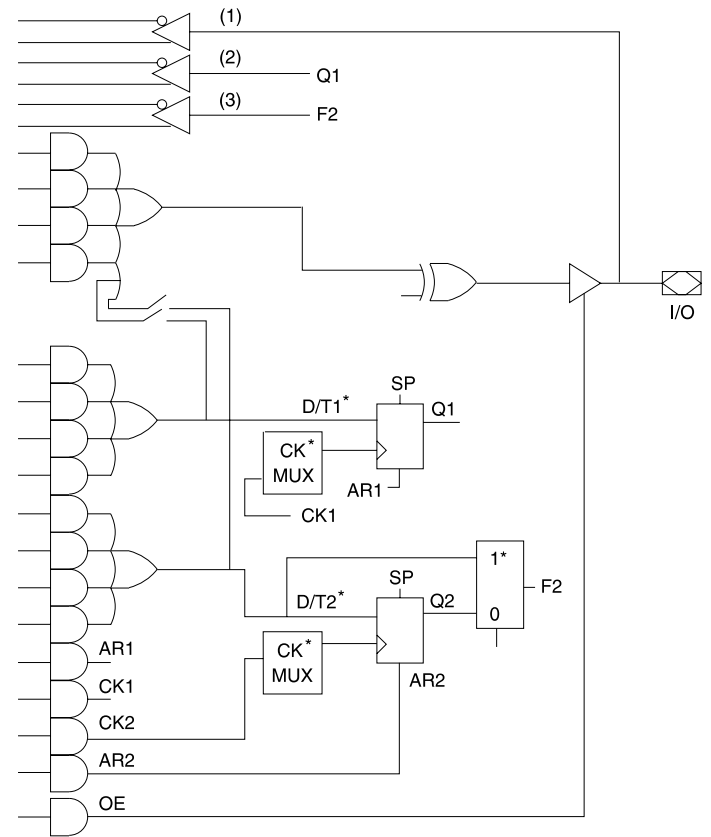


Figure 1. The ATV2500 and ATV2500B

Macrocell Output Logic, Registered



Output Logic, Combinatorial



* ATV2500B only

Pin and Node Feedbacks

Each macrocell has three feedback paths into the array, one from each of the registers and one from the pin. For a buried node, the node name is used to refer to the feedback path. For a combinatorial output, the feedback comes from the pin, so the pin name is used to refer to the feedback. For a registered output, the feedback can come either from the register or from the pin. The feedback paths are labeled (1), (2), and (3) on Figure 1. The following examples show how the different feedback paths are identified:

ABEL and Atmel-ABEL

```
O4.d = I1 # I2;
O4Q2.d = I1 & !I2;
O6 = O4      *(1)feedback from pin
# O4.fb     *(2)feedback from Q1 register(1)
# O4Q2;     *(3)feedback from buried register
```

Note: 1. For ABEL, either ".q" or ".fb" can be used to indicate the buried register feedback path. When ".q" extension is used, the software will select the Q output of the register, regardless of the output buffer polarity. When the ".fb" extension is used, the software will match the polarity of the register feedback with the output polarity by selecting either the Q or !Q output of the register.

CUPL and Atmel-CUPL

```
O4.d = I1 # I2;
O4Q2.d = I1 & !I2;
O6 = O4.io /*(1)feedback from pin */
# O4      /*(2)feedback from Q1 register */
# O4Q2;  /*(3)feedback from buried register */
```

Table 2. Node Numbers

Pin #	ABEL		CUPL	
	Q1	Q2/F2	Q1	Q2/F2
4(5)	217(221)	41(45)	65(69)	41(45)
5(6)	218(222)	42(46)	66(70)	42(46)
6(7)	219(223)	43(47)	67(71)	43(47)
7(8)	220(224)	44(48)	68(72)	44(48)
8(9)	221(225)	45(49)	69(73)	45(49)
9(10)	222(226)	46(50)	70(74)	46(50)
11(13)	223(227)	47(51)	71(75)	47(51)
12(14)	224(228)	48(52)	72(76)	48(52)
13(15)	225(229)	49(53)	73(77)	49(53)
14(16)	226(230)	50(54)	74(78)	50(54)
15(17)	227(231)	51(55)	75(79)	51(55)
16(18)	228(232)	52(56)	76(80)	52(56)
24(27)	229(233)	53(57)	77(81)	53(57)
25(28)	230(234)	54(58)	78(82)	54(58)
26(29)	231(235)	55(59)	79(83)	55(59)
27(30)	232(236)	56(60)	80(84)	56(60)
28(31)	233(237)	57(61)	81(85)	57(61)
29(32)	234(238)	58(62)	82(86)	58(62)
31(35)	235(239)	59(63)	83(87)	59(63)
32(36)	236(240)	60(64)	84(88)	60(64)
33(37)	237(241)	61(65)	85(89)	61(65)
34(38)	238(242)	62(66)	86(90)	62(66)
35(39)	239(243)	63(67)	87(91)	63(67)
36(40)	240(244)	64(68)	88(92)	64(68)

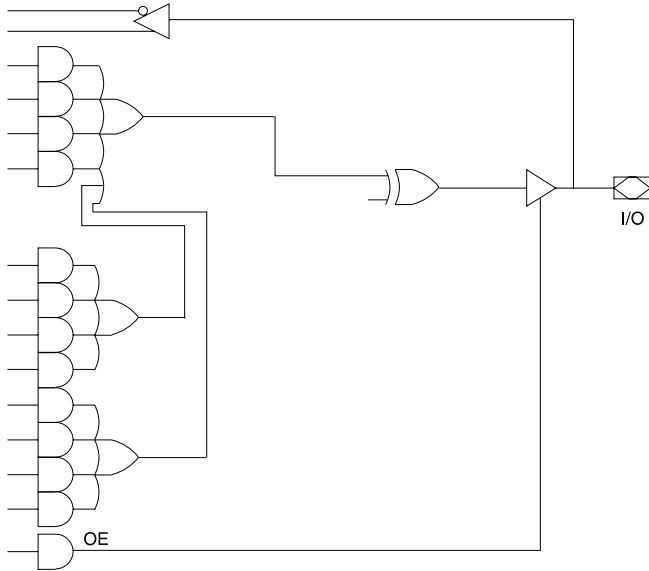
Note: Pin/node numbers: DIP(PLCC)

Macrocell Configurations

The basic macrocell configurations are shown in Figures 2 through 9. Each macrocell has three sum terms, each with four product terms. The sum terms can be combined for wider fan-in functions or separated and used for buried logic. The output can be configured as either combinatorial or registered. For a combinatorial output, the other two sum terms can be connected to buried registers. For a regis-

tered output, two of the sum terms are combined for the output and the third can be connected to a buried register. The multiple feedback paths also allow both registers to be buried, with the I/O pin used as an input pin. For the ATV2500B, the Q2 node can also be configured as a buried combinatorial node, F2, as shown in Figure 9.

Figure 2. Combinatorial Output (12 product terms)



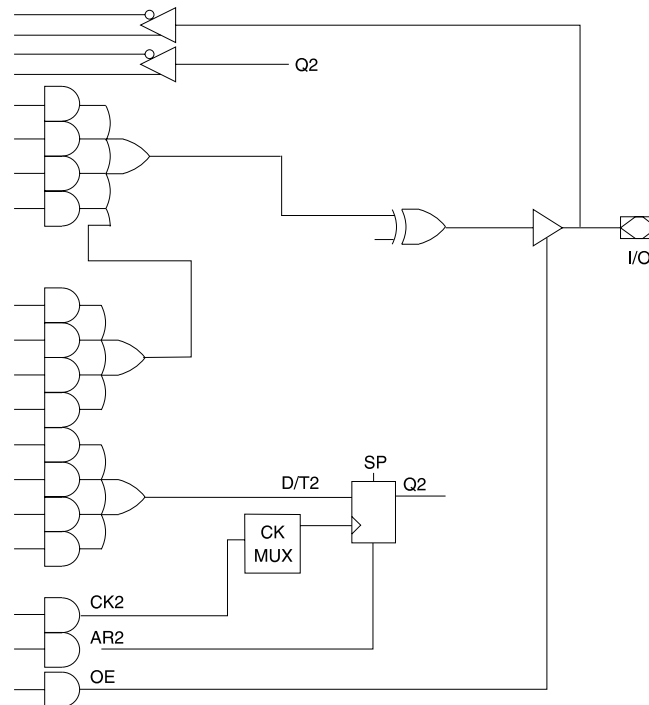
ABEL and Atmel-ABEL

```
O6 = I1 # !I2 # I3 # !I17 # I18;
```

CUPL and Atmel-CUPL

```
O6 = I1 # !I2 # I3 # !I17 # I18;
```

Figure 3. Combinatorial Output (8 product terms) plus Buried Register (4 product terms)



ABEL and Atmel-ABEL

```
O7 = I1 # !I2 # I3 # !I17 # I18;
```

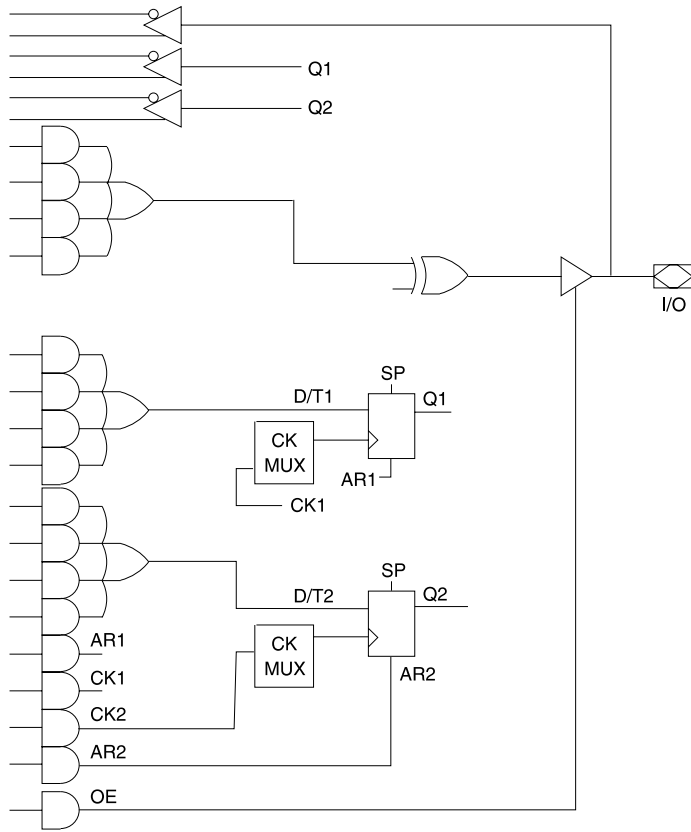
```
O7Q2.d = I2 # I3 # I17;
```

CUPL and Atmel-CUPL

```
O7 = I1 # !I2 # I3 # !I17 # I18;
```

```
O7Q2.d = I2 # I3 # I17;
```

Figure 4. Combinatorial Output (4 product terms) plus 2 Buried Registers (4 product terms each)



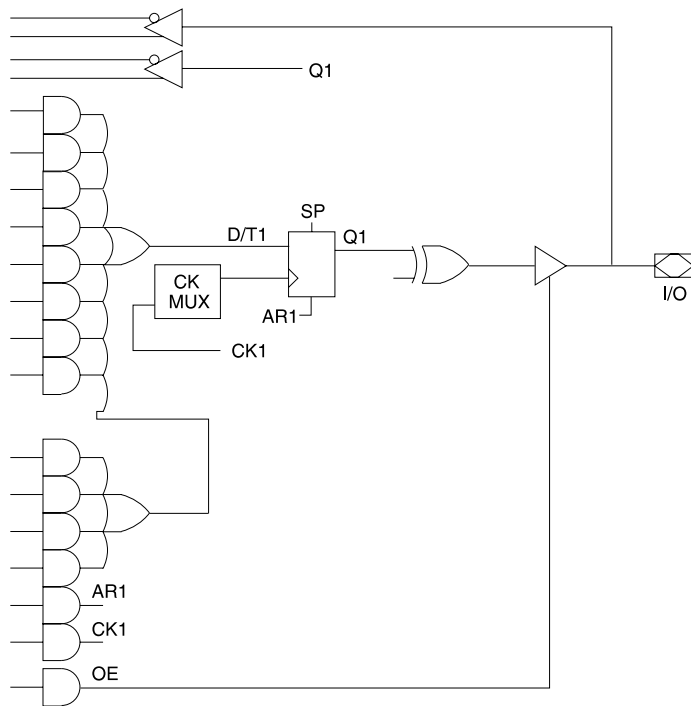
ABEL and Atmel-ABEL

```
O7 = I3 & !I17;
O7Q1.d = I1 & I2
O7Q2.d = I2 # I3 # I17;
```

CUPL and Atmel-CUPL

```
O7 = I3 & !I17;
O7Q1.d = I1 & I2
O7Q2.d = I2 # I3 # I17;
```

Figure 5. Registered Output (12 product terms)



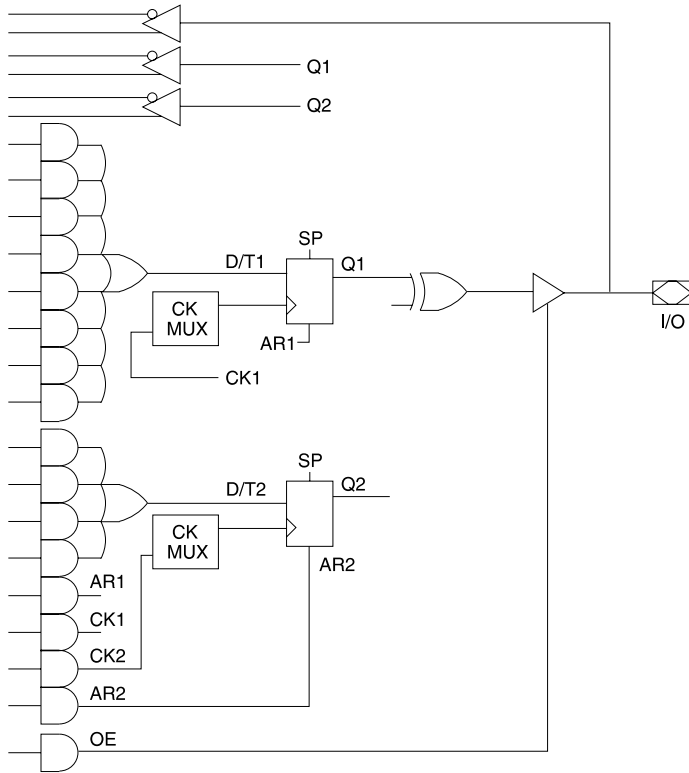
ABEL and Atmel-ABEL

```
O4.d = I1 # I2 # I3 # I17 # I18;
```

CUPL and Atmel-CUPL

```
O4.d = I1 # I2 # I3 # I17 # I18;
```

Figure 6. Registered Output (8 product terms) plus Buried Register (4 product terms)



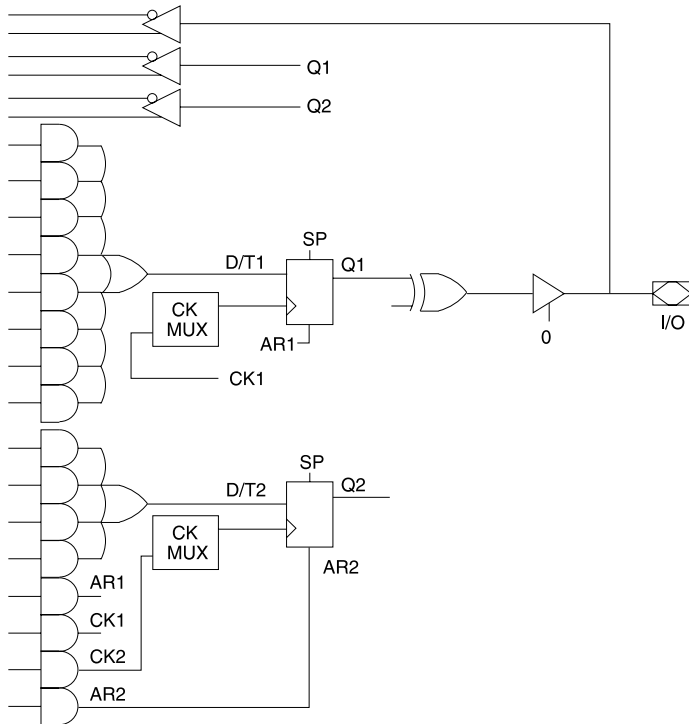
ABEL and Atmel-ABEL

```
O4.d = I1 & I2;
O4Q2.d = I3 & I17;
```

CUPL and Atmel-CUPL

```
O4.d = I1 & I2;
O4Q2.d = I3 & I17;
```

Figure 7. Both Registers Buried (Q1 - 8 product terms, Q2 - 4 product terms), I/O Pin Used as Input



ABEL and Atmel-ABEL

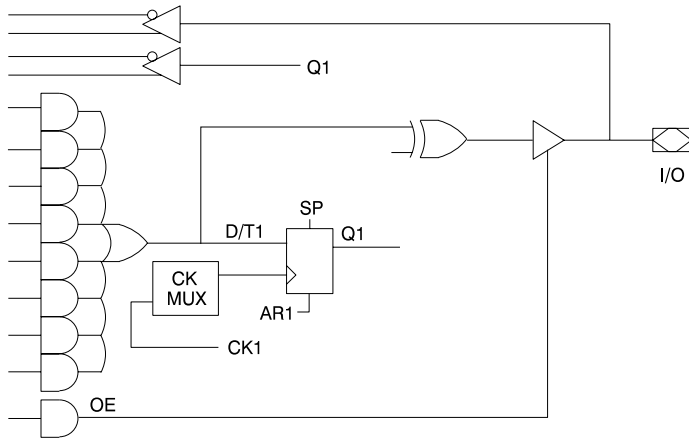
```
Declarations
O4 pin 4 istype 'reg_d';
O4Q2 node 41 istype 'reg_d';
INPUT_FUNC = O4;
REG_FUNC = O4.fb;

Equations
O4.d = INPUT_FUNC & I3;
O4.oe = 0; /*disable OE to use pin for input
O4Q2.d = REG_FUNC & I17;
```

CUPL and Atmel-CUPL

```
pin 4 = O4;
pinnode [41,65] = [O4Q2,O4Q1];
O4Q1.d = O4 & I3;
O4.oe = 'b'0; /*disable OE to use pin for input */
O4Q2.d = O4Q0 & I17;
```

Figure 8. Combinatorial Output, Q1 Register Used to Latch Data



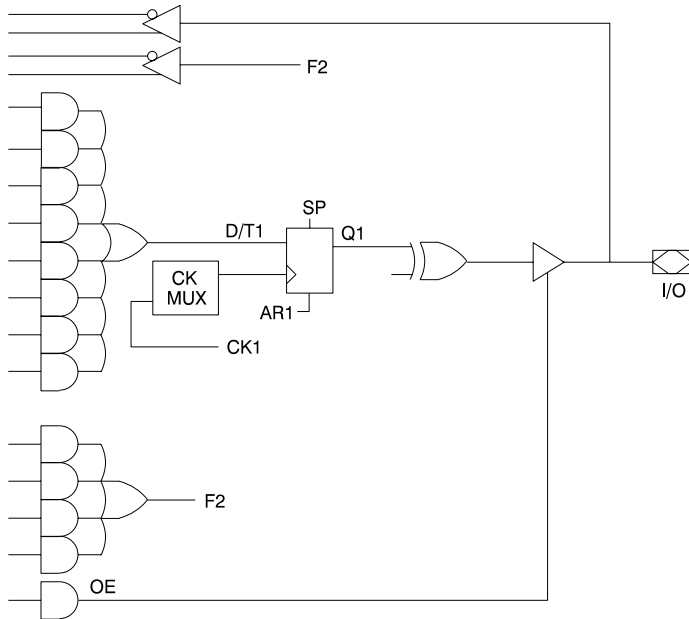
ABEL and Atmel-ABEL

```
O6 = I3;
O6.ck = CLK;
O4.d = O6.fb;  "registered O6 output
```

CUPL and Atmel-CUPL

```
O6 = I3;
O6.ck = CLK;
O4.d = O6.fb;  /* registered O6 output */
```

Figure 9. ATV2500B ONLY: Registered or Combinatorial Output plus Buried Combinatorial Node (4 product terms)



ABEL and Atmel-ABEL

```
Declarations
O4 pin 4 istype 'reg_d';
O4F2 node 41 istype 'com';

Equations
O4.d = I2 & I3;
O4F2 = I17 & I18;
```

CUPL and Atmel-CUPL

```
pin 4 = O4;
pinnode 41 = O4F2;
O4.d = I2 & I3;
O4F2 = I17 & I18;
```

For ABEL, the Q2 register is identified by a node number. The Q1 register is identified by the pin number (the Q1 node numbers should only be used for the configuration shown in Figure 4). The OE should be set to 0 to disable the outputs. The "pinname" (with no extensions) refers to the input path. The "pinname.fb" or "pinname.q" refers to the register feedback path. Another name for either the input or the register may be substituted in the Declarations section of the file, to make it clearer that they have separate

rate functions. The pin and node names will be substituted back into the equations when the file is compiled.

For CUPL, there are node numbers for both the Q2 and Q1 registers. The Q1 node name refers to the register and the pin name refers to the pin.

For this configuration, the output should be defined as combinatorial, and the equation written as combinatorial. A clock equation should also be written for the output. The registered signal which is fed back into the array is identified with ".fb" or ".q" for ABEL or ".dfb" for CUPL.

Asynchronous Reset, Synchronous Preset, and Output Enable

There is an individual asynchronous reset product term for each register. Each I/O pin has an individual output enable product term. There are eight synchronous preset product terms which are used to preset banks of four or eight registers. Table 3 shows the groups of registers connected to each of the synchronous preset product terms. Since the synchronous preset requires a clock, an individual register will only preset if it is clocked.

The following examples show how the asynchronous reset, synchronous preset, and output enable functions are defined:

ABEL and Atmel-ABEL

```
O4.ar = I1;
O4.sp = I2;    "NOTE: preset is for 8 registers
O4.oe = I3 & I17;
O5.oe = 1;
```

CUPL and Atmel-CUPL

```
O4.ar = I1;
O4.sp = I2;    /*NOTE: preset is for 8 registers */
O4.oe = I3 & I17;
O5.oe = 'b'1;
```

Programmable Polarity Control

Each I/O pin has programmable polarity control. Please refer to the application note "Using the Programmable Polarity Control" for details on using the polarity control.

Clock Options

For the ATV2500, each register has an independent clock product term. For the ATV2500B, each register can be configured to use either the clock product term, a synchronous clock pin, or a gated synchronous clock (see Figure 10).

Table 3. Synchronous Preset Groups

Preset PT	DIP Pin Number + Q1, Q2 Register
SP0	4Q1,4Q2,5Q1,5Q2,6Q1,6Q2,7Q1,7Q2
SP1	8Q1,8Q2,9Q1,9Q2
SP2	33Q1,33Q2,34Q1,34Q2,35Q1,35Q2,36Q1,36Q2
SP3	31Q1,31Q2,32Q1,32Q2
SP4	13Q1,13Q2,14Q1,14Q2,15Q1,15Q2,16Q1,16Q2
SP5	11Q1,11Q2,12Q1,12Q2
SP6	24Q1,24Q2,25Q1,25Q2,26Q1,26Q2,27Q1,27Q2
SP7	28Q1,28Q2,29Q1,29Q2

The following examples show how the clock is defined for the different modes:

ABEL and Atmel-ABEL

```
SYNC_CLK pin 1;
ASYNC_CLK,EN pin 2,3;
O4.ck = 1;          "synchronous clock pin
                   "(for ATV2500B only)

O4.ce = SYNC_CLK;
O4Q2.ck = I2 & EN;  "synchronous clock pin ANDed
                   "with clock product term

O4Q2.ce = SYNC_CLK; "(for ATV2500B only)
O5.ck = ASYNC_CLK & EN;"clock product term
```

CUPL and Atmel-CUPL

```
pin 1 = SYNC_CLK;
pin [2,3] = [ASYNC_CLK,EN];
O4.ce = 'b'1;      /*synchronous clock pin */
                   /*(for ATV2500B only) */
O4Q2.ce = I2 & EN; /*synchronous clock pin */
                   /*ANDed with clock product */
                   /*term (for ATV2500B only) */
O5.ck = ASYNC_CLK & EN;/*clock product term */
```

D-type or T-type Registers

For the ATV2500, the registers can only be configured as D-type flip-flops. For the ATV2500B, the registers can be configured as either D-type or T-type flip-flops. The following examples show how to configure the registers as either D- or T-type:

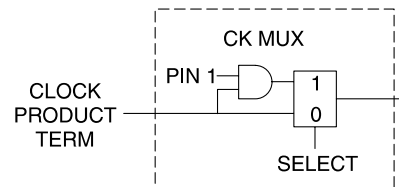
ABEL and Atmel-ABEL

```
O13 pin 13 istype 'reg_t';
O4.d = I1 & I2;
O13.t = I1 # I2;
```

CUPL and Atmel-CUPL

```
pin 13 = O13;
O4.d = I1 & I2;
O13.t = I1 # I2;
```

Figure 10. Clock Options



Example ABEL Description File

```

module use2500b;
title 'ATV2500B Example ABEL File
      Atmel Corp. - 3/27/95'
use2500b device 'P2500BC';

declarations

"T Counter
SCLK,LD,RST          pin 1,2,3;
I0,I1,I2,I3,I4,I5,I6,I7  pin 19,20,21,22,23,24,25,41;
Q0,Q1,Q2,Q3,Q4,Q5,Q6,Q7  node 45,46,47,48,49,50,51,52 istype 'reg_t';

"Grey code counter
ACLK,HOLD,OE         pin 42,43,44;
G3,G2,G1,G0         pin 5,6,7,8 istype 'reg_d,buffer';

"Seven segment display decoder
seg1,seg2,seg3,seg4  pin 9,10,13,14 istype 'com';
seg5,seg6,seg7       pin 15,16,17 istype 'com';

"Shift register
S_RST,S_LD,S_IN      pin 38,39,40;
S0,S1,S2,S3,S4,S5,S6  node 53,54,55,56,57,58,59 istype 'reg_d';
S_OUT                pin 27 istype 'reg_d,buffer';

H,L,C,X,Z,P = 1,0,.C.,.X.,.Z.,.P.;

INPUTS = [I7..I0];      "Input data
T_CNT = [Q7..Q0];      "T counter
GCODE = [G3,G2,G1,G0]; "Grey code counter
SHIFT = [S_OUT,S6,S5,S4,S3,S2,S1,S0]; "Shift register
SHIFT1 = [S6,S5,S4,S3,S2,S1,S0,S_IN];

equations

"T Counter
T_CNT.t = ((T_CNT + 1) $ T_CNT) & !LD "count
          # (T_CNT $ INPUTS) & LD;    "load
T_CNT.ck = ^hFF;
T_CNT.ce = SCLK;          "synchronous clock mode
T_CNT.ar = RST;

"Shift register
SHIFT.d = SHIFT1 & !S_LD "shift
          # INPUTS & S_LD; "load
SHIFT.ck = ACLK;         "product term clock mode
SHIFT.ar = S_RST;

"Grey code counter
GCODE.ck = !HOLD;        "gated synchronous clock mode
GCODE.ce = SCLK;
GCODE.ar = RST;
GCODE.oe = OE;

```

```
"State machine will use .q feedback
STATE_DIAGRAM GCODE
state [0,0,0,0]: goto [0,0,0,1];
state [0,0,0,1]: goto [0,0,1,1];
state [0,0,1,1]: goto [0,0,1,0];
state [0,0,1,0]: goto [0,1,1,0];
state [0,1,1,0]: goto [0,1,1,1];
state [0,1,1,1]: goto [0,1,0,1];
state [0,1,0,1]: goto [0,1,0,0];
state [0,1,0,0]: goto [1,1,0,0];
state [1,1,0,0]: goto [1,1,0,1];
state [1,1,0,1]: goto [1,1,1,1];
state [1,1,1,1]: goto [1,1,1,0];
state [1,1,1,0]: goto [1,0,1,0];
state [1,0,1,0]: goto [1,0,1,1];
state [1,0,1,1]: goto [1,0,0,1];
state [1,0,0,1]: goto [1,0,0,0];
state [1,0,0,0]: goto [0,0,0,0];
```

```
"Seven segment display decoder
"Use register feedback path
```

```
truth_table (
[GCODE.fb] -> [seg1,seg2,seg3,seg4,seg5,seg6,seg7])
[ 0 ] -> [ 1, 0, 1, 1, 1, 1, 1 ];
[ 1 ] -> [ 0, 0, 0, 1, 1, 0, 0 ];
[ 2 ] -> [ 1, 1, 1, 1, 0, 0, 1 ];
[ 3 ] -> [ 1, 1, 1, 1, 1, 0, 0 ];
[ 4 ] -> [ 0, 1, 0, 1, 1, 1, 0 ];
[ 5 ] -> [ 1, 1, 1, 0, 1, 1, 0 ];
[ 6 ] -> [ 1, 1, 1, 0, 1, 1, 1 ];
[ 7 ] -> [ 1, 0, 0, 1, 1, 0, 0 ];
[ 8 ] -> [ 1, 1, 1, 1, 1, 1, 1 ];
[ 9 ] -> [ 1, 1, 0, 1, 1, 1, 0 ];
[ 10 ] -> [ 1, 1, 0, 1, 1, 1, 1 ];
[ 11 ] -> [ 0, 1, 1, 0, 1, 1, 1 ];
[ 12 ] -> [ 1, 0, 1, 0, 0, 1, 1 ];
[ 13 ] -> [ 0, 1, 1, 1, 1, 0, 1 ];
[ 14 ] -> [ 1, 1, 1, 0, 0, 1, 1 ];
[ 15 ] -> [ 1, 1, 0, 0, 0, 1, 1 ];
```

```
@@RADIX16;
@@CONST CNT = 0;
```

```
TEST_VECTORS (
[SCLK,RST,LD,INPUTS]->[T_CNT]);
[0, 1, 0, 000 ]->[000 ];
@@REPEAT OFF{
@@CONST CNT=CNT+1;
[C, 0, 0, 000 ]->[CNT ];}
[C, 0, 1, 0AB ]->[0AB ];
[C, 0, 0, 000 ]->[0AC ];
```

```
TEST_VECTORS (
[SCLK,HOLD,RST,OE]-[G3,G2,G1,G0,seg1,seg2,seg3,seg4,seg5,seg6,seg7])
[ 0, 0, 1, 1 ]->[0, 0, 0, 0, 1, 0, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[0, 0, 0, 1, 0, 0, 0, 1, 1, 0, 0 ];
[ C, 0, 0, 1 ]->[0, 0, 1, 1, 1, 1, 1, 1, 1, 0, 0 ];
[ C, 0, 0, 1 ]->[0, 0, 1, 0, 1, 1, 1, 1, 1, 0, 1 ];
[ C, 0, 0, 1 ]->[0, 1, 1, 0, 1, 1, 1, 0, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[0, 1, 1, 1, 1, 0, 0, 1, 1, 0, 0 ];
[ C, 0, 0, 1 ]->[0, 1, 0, 1, 1, 1, 1, 0, 1, 1, 0 ];
[ C, 0, 0, 1 ]->[0, 1, 0, 0, 0, 1, 0, 1, 1, 1, 0 ];
```

```
[ C, 0, 0, 1 ]->[1, 1, 0, 0, 1, 0, 1, 0, 0, 1, 1 ];
[ C, 0, 0, 1 ]->[1, 1, 0, 1, 0, 1, 1, 1, 1, 0, 1 ];
[ C, 0, 0, 1 ]->[1, 1, 1, 1, 1, 1, 1, 0, 0, 1, 1 ];
[ C, 0, 0, 1 ]->[1, 1, 1, 0, 1, 1, 1, 0, 0, 1, 1 ];
[ C, 0, 0, 1 ]->[1, 0, 1, 0, 1, 1, 0, 1, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[1, 0, 1, 1, 0, 1, 1, 0, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[1, 0, 0, 1, 1, 1, 0, 1, 1, 1, 0 ];
[ C, 0, 0, 1 ]->[1, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[0, 0, 0, 0, 1, 0, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1 ]->[0, 0, 0, 1, 0, 0, 0, 1, 1, 0, 0 ];
[ C, 1, 0, 1 ]->[0, 0, 0, 1, 0, 0, 0, 1, 1, 0, 0 ];
[ C, 0, 0, 0 ]->[Z, Z, Z, Z, 1, 1, 1, 1, 1, 0, 0 ];
```

```
TEST_VECTORS (
[ACLK,S_LD,S_RST,S_IN,INPUTS]-[S0,S1,S2,S3,S4,S5,S6,S_OUT])
[ 0, 0, 1, 0, 000 ]->[0, 0, 0, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 0, 0, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 1, 0, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 1, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 1, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 0, 1, 0, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 0, 0, 1, 0, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 0, 0, 0, 1, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 0, 0, 0, 0, 1, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 0, 0, 0, 0, 0, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 0, 0, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 0, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 0, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 0, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 0, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 0, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 1, 0, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 1, 1, 0 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 0, 000 ]->[0, 1, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 0, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 0, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 0, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 0, 1, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 0, 1, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 0, 1, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 1, 0, 1 ];
[ C, 0, 0, 1, 000 ]->[1, 1, 1, 1, 1, 1, 1, 1, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 1, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 1, 1, 1, 1, 1, 1, 1 ];
[ C, 0, 0, 0, 000 ]->[0, 0, 0, 1, 1, 1, 1, 1, 1 ];
[ C, 1, 0, 0, 055 ]->[1, 0, 1, 0, 1, 0, 1, 0, 0 ];
[ C, 0, 0, 0, 000 ]->[0, 1, 0, 1, 0, 1, 0, 1, 0 ];
```

END

Example CUPL Description File

```

Name      USE2500B;
Partno    N/A;
Date      3/27/95;
Rev.      -;
Designer  ;
Company   Atmel;
Assembly  -;
Location  -;
Device    V2500BLCC;

/* Example V2500B CUPL file */

/* T Counter */
pin [1,2,3] = SCLK,LD,RST;
pin [19..25,41] = [I0..I7];
pinnode [45..52] = [Q0..Q7];

/* Grey code counter */
pin [42,43,44] = [ACLK,HOLD,OE];
pin [5..8] = [G3..G0];

/* Seven segment display decoder */
pin [9,10,13..17] = [1seg,2seg,3seg,4seg,5seg,6seg,7seg];

/* Shift register */
pin [38,39,40] = [S_RST,S_LD,S_IN];
pinnode [53..59] = [S0..S6];
pinnode 60 = S_OUT;

field INPUTS = [I7..I0]; /* Input data */
field T_CNT = [Q7..Q0]; /* T counter */
field GCODE = [G3..G0]; /* Grey code counter */
field SHIFT = [S_OUT,S6..S0]; /* Shift register */
field SHIF1 = [S6..S0,S_IN];

/* T Counter */
Q0.t = !LD
      # (Q0 $ I0) & LD;
Q1.t = !LD & Q0
      # LD & (Q1 $ I1);
Q2.t = !LD & Q1 & Q0
      # LD & (Q2 $ I2);
Q3.t = !LD & Q2 & Q1 & Q0
      # LD & (Q3 $ I3);
Q4.t = !LD & Q3 & Q2 & Q1 & Q0
      # LD & (Q4 $ I4);
Q5.t = !LD & Q4 & Q3 & Q2 & Q1 & Q0
      # LD & (Q5 $ I5);
Q6.t = !LD & Q5 & Q4 & Q3 & Q2 & Q1 & Q0
      # LD & (Q6 $ I6);
Q7.t = !LD & Q6 & Q5 & Q4 & Q3 & Q2 & Q1 & Q0
      # LD & (Q7 $ I7);
T_CNT.ce = 'h'FF; /* synchronous clock mode */
T_CNT.ar = RST;

```

```

/* Shift register */
SHIFT.d = SHIFT1 & !S_LD /* shift */
      # INPUTS & S_LD; /* load */
SHIFT.ck = ACLK; /* product term clock mode */
SHIFT.ar = S_RST;

/* Greyscale counter */
GCODE.ce = !HOLD; /* gated synchronous clock mode */
GCODE.ar = RST;
GCODE.oe = OE;

/* State machine will use register feedback path */
SEQUENCE GCODE {
present 'b'0000 next 'b'0001;
present 'b'0001 next 'b'0011;
present 'b'0011 next 'b'0010;
present 'b'0010 next 'b'0110;
present 'b'0110 next 'b'0111;
present 'b'0111 next 'b'0101;
present 'b'0101 next 'b'0100;
present 'b'0100 next 'b'1100;
present 'b'1100 next 'b'1101;
present 'b'1101 next 'b'1111;
present 'b'1111 next 'b'1110;
present 'b'1110 next 'b'1010;
present 'b'1010 next 'b'1011;
present 'b'1011 next 'b'1001;
present 'b'1001 next 'b'1000;
present 'b'1000 next 'b'0000;}

/* Seven segment display decoder */
TABLE GCODE = [1seg,2seg,3seg,4seg,5seg,6seg,7seg] {
0 => 'b'1011111;
1 => 'b'0001100;
2 => 'b'1111001;
3 => 'b'1111100;
4 => 'b'0101110;
5 => 'b'1110110;
6 => 'b'1110111;
7 => 'b'1001100;
8 => 'b'1111111;
9 => 'b'1101110;
A => 'b'1101111;
B => 'b'0110111;
C => 'b'1010011;
D => 'b'0111101;
E => 'b'1110011;
F => 'b'1100011; }

```



```
CUPL Simulation Input File (Use 2500B.SI)
Name          USE2500B;
Partno        N/A;
Date          3/27/95;
Rev.          -;
Designer      PLD Expert;
Company       Atmel;
Assembly      -;
Location      -;
Device        V2500BLCC;
```

```
FIELD SEVSEG=[1seg,2seg,3seg,4seg,5seg,6seg,7seg];
FIELD TST_SHIFT=[S0,S1,S2,S3,S4,S5,S6,S_OUT];
```

```
ORDER: SCLK,%1,RST,%1,LD,%1,HOLD,%1,OE,%1,INPUTS,%1,
        ACLK,%1,S_LD,%1,S_RST,%1,S_IN,%2,
        T_CNT,%2,GCODE,%2,SEVSEG,%2,TST_SHIFT;
```

```
BASE: hex;
```

```
VECTORS:
```

```
/* Test T-counter */
0 1 0 1 1 '00' 0 0 0 0 "00"  " "  " "  " "
$REPEAT 255;
C 0 0 1 1 '00' 0 0 0 0 " "  " "  " "  " "
C 0 1 1 1 'AB' 0 0 0 0 "AB"  " "  " "  " "
C 0 0 1 1 '00' 0 0 0 0 "AC"  " "  " "  " "
/* Test greycode counter and seven segment decoder */
0 1 0 0 1 '00' 0 0 0 0 " "  "0"  HLHHHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "1"  LLLHHLL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "3"  HHHHHLL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "2"  HHHHLLH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "6"  HHHLHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "7"  HLLHHLL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "5"  HHHLHHL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "4"  LHLHHHL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "C"  HLHLLHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "D"  LHHHHLH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "F"  HLLLLHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "E"  HHHLLHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "A"  HHLHHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "B"  LHHLHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "9"  HHLHHHL  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "8"  HHHHHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "0"  HLHHHHH  " "
C 0 0 0 1 '00' 0 0 0 0 " "  "1"  LLLHHLL  " "
C 0 0 1 1 '00' 0 0 0 0 " "  "1"  LLLHHLL  " "
C 0 0 0 0 '00' 0 0 0 0 " "  "Z"  HHHHHLL  " "
/* Test shift register */
0 0 0 0 1 '00' 0 0 1 0 " "  " "  " "  LLLLLLLL
0 0 0 0 1 '00' C 0 0 1 " "  " "  " "  HLLLLLLL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LHLLLLLL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLHLLLLL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLLHLLLL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLLLHLLL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLLLHLHL
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLLLLLH
0 0 0 0 1 '00' C 0 0 0 " "  " "  " "  LLLLLLH
0 0 0 0 1 '00' C 0 0 1 " "  " "  " "  HLLLLLLL
0 0 0 0 1 '00' C 0 0 1 " "  " "  " "  HHLLLLLL
0 0 0 0 1 '00' C 0 0 1 " "  " "  " "  HHHLLLLL
0 0 0 0 1 '00' C 0 0 1 " "  " "  " "  HHHHLLLL
```

```

0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHLLL
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHLLL
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHHHL
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHHHH
0 0 0 0 1 '00' C 0 0 0 "*" "*" "*" LHHHHHH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HLHHHHH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHLHHHH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHLHHH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHLHH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHHLH
0 0 0 0 1 '00' C 0 0 1 "*" "*" "*" HHHHHHL
0 0 0 0 1 '00' C 0 0 0 "*" "*" "*" LHHHHHH
0 0 0 0 1 '00' C 0 0 0 "*" "*" "*" LLHHHHH
0 0 0 0 1 '00' C 0 0 0 "*" "*" "*" LLLHHHH
0 0 0 0 1 '55' C 1 0 0 "*" "*" "*" HLHLHLH
0 0 0 0 1 '00' C 0 0 0 "*" "*" "*" LHLHLHL

```



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