

## XC4000EX Switching Characteristics

### Definition of Terms

In the following tables, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

**Advance:** Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or device families. Values are subject to change. Use as estimates, not for production.

**Preliminary:** Based on preliminary characterization. Further changes are not expected.

**Unmarked:** Specifications not identified as either Advance or Preliminary are to be considered Final.

All specifications subject to change without notice.

### XC4000EX Absolute Maximum Ratings

Symbol	Description	Value	Units
V <sub>CC</sub>	Supply voltage relative to GND	-0.5 to +7.0	V
V <sub>IN</sub>	Input voltage relative to GND (Note 1)	-0.5 to V <sub>CC</sub> +0.5	V
V <sub>TS</sub>	Voltage applied to 3-state output (Note 1)	-0.5 to V <sub>CC</sub> +0.5	V
V <sub>CCt</sub>	Longest Supply Voltage Rise Time from 1 V to 4 V	50	ms
T <sub>STG</sub>	Storage temperature (ambient)	-65 to +150	°C
T <sub>SOL</sub>	Maximum soldering temperature (10 s @ 1/16 in. = 1.5 mm)	+260	°C
T <sub>J</sub>	Junction temperature	Ceramic packages	+150 °C
		Plastic packages	+125 °C

Notes: 1. Maximum DC overshoot or undershoot

above V<sub>CC</sub> or below GND must be limited to either 0.5 V or 10 mA, whichever is easier to achieve. During transitions, the device pins may undershoot to -2.0 V or overshoot to V<sub>CC</sub> + 2.0 V, provided this over- or undershoot lasts less than 20 ns.

- Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.

### XC4000EX Recommended Operating Conditions

Symbol	Description	Min	Max	Units	
V <sub>CC</sub>	Supply voltage relative to GND, T <sub>J</sub> = 0 °C to +85°C	Commercial	4.75	5.25	V
	Supply voltage relative to GND, T <sub>J</sub> = -40°C to +100°C	Industrial	4.5	5.5	V
V <sub>IH</sub>	High-level input voltage	TTL inputs	2.0	V <sub>CC</sub>	V
		CMOS inputs	70%	100%	V <sub>CC</sub>
V <sub>IL</sub>	Low-level input voltage	TTL inputs	0	0.8	V
		CMOS inputs	0	20%	V <sub>CC</sub>
T <sub>IN</sub>	Input signal transition time		250	ns	

Notes: At junction temperatures above those listed as Operating Conditions, all delay parameters increase by 0.35% per °C. Input and output measurement thresholds for TTL are 1.5 V. Input and output measurement thresholds for CMOS are 2.5 V. All timing parameters are specified for Commercial temperature range only.

## XC4000EX DC Characteristics Over Recommended Operating Conditions

Symbol	Description		Min	Max	Units
V <sub>OH</sub>	High-level output voltage @ I <sub>OH</sub> = -4.0 mA, V <sub>CC</sub> min	TTL outputs	2.4		V
	High-level output voltage @ I <sub>OH</sub> = -1.0 mA	CMOS outputs	V <sub>CC</sub> -0.5		V
V <sub>OL</sub>	Low-level output voltage @ I <sub>OL</sub> = 12.0 mA, V <sub>CC</sub> min (Note 1)	TTL outputs		0.4	V
		CMOS outputs		0.4	V
V <sub>DR</sub>	Data Retention Supply Voltage (below which configuration data may be lost)		3.0		V
I <sub>CCO</sub>	Quiescent FPGA supply current (Note 2)			25	mA
I <sub>L</sub>	Input or output leakage current		-10	+10	μA
C <sub>IN</sub>	Input capacitance (sample tested)	BGA, SBGA, PQ, HQ, MQ packages		10	pF
		PGA packages		16	pF
I <sub>RPU</sub>	Pad pull-up (when selected) @ V <sub>in</sub> = 0 V (sample tested)		0.02	0.25	mA
I <sub>RPD</sub>	Pad pull-down (when selected) @ V <sub>in</sub> = 5.5 V (sample tested)		0.02	0.25	mA
I <sub>RLL</sub>	Horizontal Longline pull-up (when selected) @ logic Low		0.3	2.0	mA

Note 1: With up to 64 pins simultaneously sinking 12 mA.

Note 2: With no output current loads, no active input or Longline pull-up resistors, all package pins at V<sub>CC</sub> or GND.

## XC4000EX Global Buffer Switching Characteristic Guidelines

Testing of the switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values where one global clock input drives one vertical clock line in each accessible column, and where all accessible IOB and CLB flip-flops are clocked by the global clock net.

When fewer vertical clock lines are connected, the clock distribution is faster; when multiple clock lines per column are driven from the same global clock, the delay is longer. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature).

			Speed Grade				Units
Description	Symbol	Device	-4 Max	-3 Max	-2 Max	-1 Max	
From pad through Global Low Skew buffer, to any clock K	T <sub>GLS</sub>	XC4028EX	9.2	7.5	6.4		ns
		XC4036EX	9.8	7.9	7.1		ns
From pad through Global Early buffer, to any clock K in same quadrant	T <sub>GE</sub>	XC4028EX	5.7	4.4	4.2		ns
		XC4036EX	5.9	4.6	4.4		ns
			<b>Preliminary</b>				

## XC4000EX Longline and Wide Decoder Timing Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted. Fewer than the specified number of pullup resistors can be used, if desired. Using fewer pullups reduces power consumption but increases delays. Use the static timing analyzer to determine delays if fewer pullups are used.

### XC4000EX Horizontal Longline Switching Characteristic Guidelines

Description	Speed Grade		-4	-3	-2	-1	Units
	Symbol	Device	Max	Max	Max	Max	
<b>TBUF driving a Horizontal Longline</b>							
I going High or Low to Horizontal Longline going High or Low, while T is Low. Buffer is constantly active.	T <sub>IO1</sub>	XC4028EX	13.7	11.3	10.9		ns
		XC4036EX	16.5	13.6	13.2		ns
T going Low to Horizontal Longline going from resistive pull-up or floating High to active Low. TBUF configured as open-drain or active buffer with I = Low.	T <sub>ON</sub>	XC4028EX	14.7	12.1	11.7		ns
		XC4036EX	17.4	14.4	14.0		ns
T going High to Horizontal Longline going from Low to High, pulled up by two resistors. (Note 1)	T <sub>PU2</sub>	XC4028EX					ns
		XC4036EX					ns
<b>TBUF driving Half a Horizontal Longline</b>							
I going High or Low to half of a Horizontal Longline going High or Low, while T is Low. Buffer is constantly active.	T <sub>HIO1</sub>	XC4028EX	6.3	5.6	4.6		ns
		XC4036EX	7.3	6.0	5.7		ns
T going Low to half of a Horizontal Longline going from resistive pull-up or floating High to active Low. TBUF configured as open-drain or active buffer with I = Low.	T <sub>HON</sub>	XC4028EX	7.2	6.4	5.4		ns
		XC4036EX	8.2	6.8	6.5		ns
T going High to half of a Horizontal Longline going from Low to High, pulled up by four resistors. (Note 1)	T <sub>HPU4</sub>	XC4028EX					ns
		XC4036EX					ns
			<b>Preliminary</b>				

Note: These values include a minimum load of one output, spaced as far as possible from the activated pullup(s). Use the static timing analyzer to determine the delay for each destination.

### XC4000EX Wide Decoder Switching Characteristic Guidelines

Description	Speed Grade		-4	-3	-2	-1	Units
	Symbol	Device	Max	Max	Max	Max	
Full length, two pull-ups, inputs from IOB I-pins	T <sub>WAF2</sub>	XC4028EX					ns
		XC4036EX					ns
Full length, two pull-ups, inputs from internal logic	T <sub>WAF2L</sub>	XC4028EX					ns
		XC4036EX					ns
Half length, two pull-ups, inputs from IOB I-pins	T <sub>WAO2</sub>	XC4028EX					ns
		XC4036EX					ns
Half length, two pull-ups, inputs from internal logic	T <sub>WAO2L</sub>	XC4028EX					ns
		XC4036EX					ns
			<b>Preliminary</b>				

Notes: These delays are specified from the decoder input to the decoder output.

## XC4000EX CLB Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted.

Description	Speed Grade	-4		-3		-2		-1		Units
	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Combinatorial Delays</b>										
F/G inputs to X/Y outputs	T <sub>ILO</sub>		2.2		1.8		1.5			ns
F/G inputs via H' to X/Y outputs	T <sub>IHO</sub>		3.8		3.2		2.7			ns
F/G inputs via transparent latch to Q outputs	T <sub>ITO</sub>		3.2		2.7		2.5			ns
C inputs via SR/H0 via H' to X/Y outputs	T <sub>HH0O</sub>		3.6		3.0		2.5			ns
C inputs via H1 via H' to X/Y outputs	T <sub>HH1O</sub>		3.0		2.5		2.3			ns
C inputs via DIN/H2 via H' to X/Y outputs	T <sub>HH2O</sub>		3.6		3.0		2.5			ns
C inputs via EC, DIN/H2 to YQ, XQ output (bypass)	T <sub>CBYP</sub>		2.0		1.6		1.4			ns
<b>CLB Fast Carry Logic</b>										
Operand inputs (F1, F2, G1, G4) to COUT	T <sub>OPCY</sub>		2.5		2.2		1.9			ns
Add/Subtract input (F3) to COUT	T <sub>ASCY</sub>		4.1		3.6		3.1			ns
Initialization inputs (F1, F3) to COUT	T <sub>INCY</sub>		1.9		1.6		1.4			ns
CIN through function generators to X/Y outputs	T <sub>SUM</sub>		3.0		2.6		2.2			ns
C <sub>IN</sub> to C <sub>OUT</sub> , bypass function generators	T <sub>BYP</sub>		0.60		0.50		0.40			ns
Carry Net Delay, C <sub>OUT</sub> to C <sub>IN</sub>	T <sub>NET</sub>		0.18		0.15		0.15			ns
<b>Sequential Delays</b>										
Clock K to Flip-Flop outputs Q	T <sub>CKO</sub>		2.2		1.9		1.7			ns
Clock K to Latch outputs Q	T <sub>CKLO</sub>		2.2		1.9		1.7			ns
<b>Setup Time before Clock K</b>										
F/G inputs	T <sub>ICK</sub>	1.3		1.1		1.1				ns
F/G inputs via H'	T <sub>IHCK</sub>	3.0		2.5		2.2				ns
C inputs via H0 through H'	T <sub>HH0CK</sub>	2.8		2.3		2.0				ns
C inputs via H1 through H'	T <sub>HH1CK</sub>	2.2		1.8		1.8				ns
C inputs via H2 through H'	T <sub>HH2CK</sub>	2.8		2.3		2.0				ns
C inputs via DIN	T <sub>DICK</sub>	1.2		0.9		0.9				ns
C inputs via EC	T <sub>ECCK</sub>	1.2		1.0		0.9				ns
C inputs via S/R, going Low (inactive)	T <sub>RCK</sub>	0.8		0.7		0.6				ns
CIN input via F'/G'	T <sub>CCK</sub>	2.2		1.8		2.1				ns
CIN input via F'/G' and H'	T <sub>CHCK</sub>	3.9		3.2		3.2				ns
<b>Hold Time after Clock K</b>										
F/G inputs	T <sub>CKI</sub>	0		0		0				ns
F/G inputs via H'	T <sub>CKIH</sub>	0		0		0				ns
C inputs via SR/H0 through H'	T <sub>CKHH0</sub>	0		0		0				ns
C inputs via H1 through H'	T <sub>CKHH1</sub>	0		0		0				ns
C inputs via DIN/H2 through H'	T <sub>CKHH2</sub>	0		0		0				ns
C inputs via DIN/H2	T <sub>CKDI</sub>	0		0		0				ns
C inputs via EC	T <sub>CKEC</sub>	0		0		0				ns
C inputs via SR, going Low (inactive)	T <sub>CKR</sub>	0		0		0				ns
<b>Clock</b>										
Clock High time	T <sub>CH</sub>	3.5		3.0		3.0				ns
Clock Low time	T <sub>CL</sub>	3.5		3.0		3.0				ns
<b>Set/Reset Direct</b>										
Width (High)	T <sub>RPW</sub>	3.5		3.0		3.0				ns
Delay from C inputs via S/R, going High to Q	T <sub>RIO</sub>		4.5		3.8		3.6			ns
<b>Global Set/Reset</b>										
Minimum GSR Pulse Width	T <sub>MRW</sub>		13.0		11.5		11.5			ns
Delay from GSR input to any Q (XC4028EX)	T <sub>MRQ</sub>		22.8		19.0		19.0			ns
Delay from GSR input to any Q (XC4036EX)	T <sub>MRQ</sub>		24.0		21.0		21.0			ns
<b>Toggle Frequency )</b> (for export control purposes)	F <sub>TOG</sub>		143		166		166			MHz

Preliminary

### XC4000EX CLB RAM Synchronous (Edge-Triggered) Write Operation Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted.

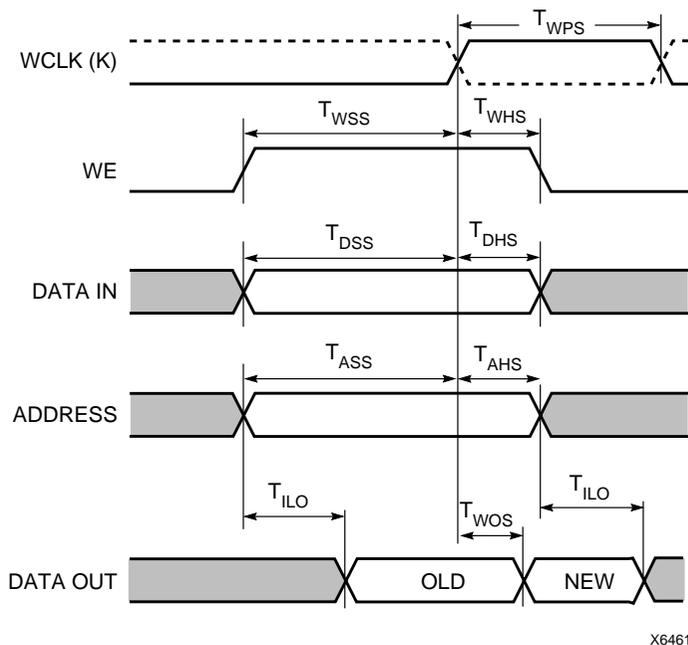
Single Port RAM	Speed Grade		-4		-3		-2		-1		Units
	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time (clock K period)	16x2	T <sub>WCS</sub>	11.0		9.0		9.0				ns
	32x1	T <sub>WCTS</sub>	11.0		9.0		9.0				ns
Clock K pulse width (active edge)	16x2	T <sub>WPS</sub>	5.5		4.5		4.5				ns
	32x1	T <sub>WPTS</sub>	5.5		4.5		4.5				ns
Address setup time before clock K	16x2	T <sub>ASS</sub>	2.7		2.3		2.2				ns
	32x1	T <sub>ASTS</sub>	2.6		2.2		2.2				ns
Address hold time after clock K	16x2	T <sub>AHS</sub>	0		0		0				ns
	32x1	T <sub>AHTS</sub>	0		0		0				ns
DIN setup time before clock K	16x2	T <sub>DSS</sub>	2.4		2.0		2.0				ns
	32x1	T <sub>DSTS</sub>	2.9		2.5		2.5				ns
DIN hold time after clock K	16x2	T <sub>DHS</sub>	0		0		0				ns
	32x1	T <sub>DHTS</sub>	0		0		0				ns
WE setup time before clock K	16x2	T <sub>WSS</sub>	2.3		2.0		2.0				ns
	32x1	T <sub>WSTS</sub>	2.1		1.8		1.8				ns
WE hold time after clock K	16x2	T <sub>WHS</sub>	0		0		0				ns
	32x1	T <sub>WHTS</sub>	0		0		0				ns
Data valid after clock K	16x2	T <sub>WOS</sub>		8.2		6.8		6.8			ns
	32x1	T <sub>WOTS</sub>		10.1		8.4		8.2			ns
<b>Preliminary</b>											

Notes: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.  
Applicable Read timing specifications are identical to Level-Sensitive Read timing.

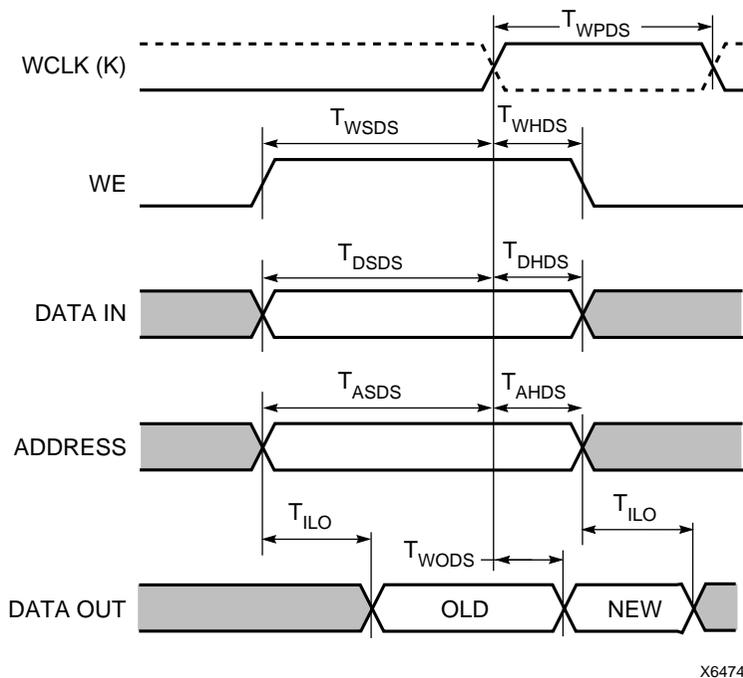
Dual-Port RAM	Speed Grade		-4		-3		-2		-1		Units
	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time (clock K period)	16x1	T <sub>WCDS</sub>	11.0		9.0		9.0				ns
Clock K pulse width (active edge)	16x1	T <sub>WPDS</sub>	5.5		4.5		4.5				ns
Address setup time before clock K	16x1	T <sub>ASDS</sub>	3.1		2.6		2.5				ns
Address hold time after clock K	16x1	T <sub>AHDS</sub>	0		0		0				ns
DIN setup time before clock K	16x1	T <sub>DSDS</sub>	2.9		2.5		2.5				ns
DIN hold time after clock K	16x1	T <sub>DHDS</sub>	0		0		0				ns
WE setup time before clock K	16x1	T <sub>WSDS</sub>	2.1		1.8		1.8				ns
WE hold time after clock K	16x1	T <sub>WHDS</sub>	0		0		0				ns
Data valid after clock K	16x1	T <sub>WODS</sub>		9.4		7.8		7.8			ns
<b>Preliminary</b>											

Note: Applicable Read timing specifications are identical to Level-Sensitive Read timing.

### XC4000EX CLB RAM Synchronous (Edge-Triggered) Write Timing



### XC4000EX CLB Dual-Port RAM Synchronous (Edge-Triggered) Write Timing



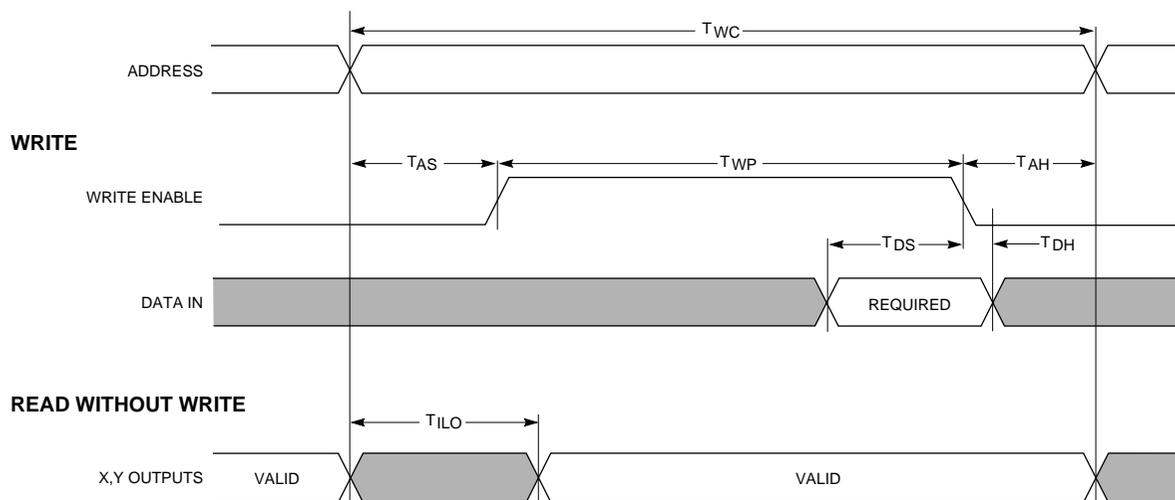
### XC4000EX CLB RAM Asynchronous (Level-Sensitive) Write and Read Operation Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted.

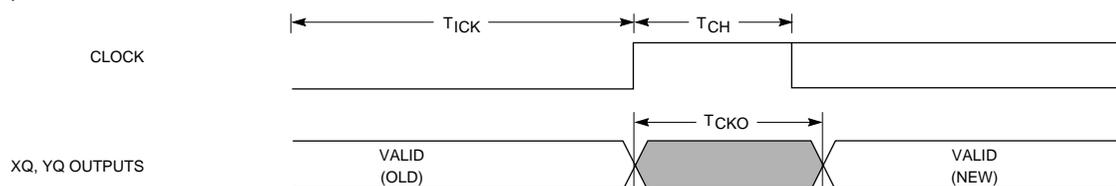
Speed Grade			-4		-3		-2		-1		Units
Description	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time	16x2	$T_{WC}$	10.6		9.2		8.0				ns
	32x1	$T_{WCT}$	10.6		9.2		8.0				ns
Write Enable pulse width (High)	16x2	$T_{WP}$	5.3		4.6		4.0				ns
	32x1	$T_{WPT}$	5.3		4.6		4.0				ns
Address setup time before WE	16x2	$T_{AS}$	2.8		2.4		2.0				ns
	32x1	$T_{AST}$	2.9		2.5		2.0				ns
Address hold time after end of WE	16x2	$T_{AH}$	1.7		1.4		1.4				ns
	32x1	$T_{AHT}$	1.7		1.4		1.4				ns
DIN setup time before end of WE	16x2	$T_{DS}$	1.1		0.9		0.8				ns
	32x1	$T_{DST}$	1.1		0.9		0.8				ns
DIN hold time after end of WE	16x2	$T_{DH}$	6.6		5.7		5.0				ns
	32x1	$T_{DHT}$	6.6		5.7		5.0				ns
<b>Read Operation</b>											
Address read cycle time	16x2	$T_{RC}$	4.5		3.1		3.1				ns
	32x1	$T_{RCT}$	6.5		5.5		5.5				ns
Data valid after address change (no Write Enable)	16x2	$T_{ILO}$		2.2		1.8		1.5			ns
	32x1	$T_{IHO}$		3.8		3.2		2.7			ns
<b>Read Operation, Clocking Data into Flip-Flop</b>											
Address setup time before clock K	16x2	$T_{ICK}$	1.5		1.2		1.2				ns
	32x1	$T_{IHCK}$	3.2		2.6		2.6				ns
<b>Read During Write</b>											
Data valid after WE goes active (DIN stable before WE)	16x2	$T_{WO}$		6.5		5.7		4.9			ns
	32x1	$T_{WOT}$		7.4		6.5		5.6			ns
Data valid after DIN (DIN changes during WE)	16x2	$T_{DO}$		7.7		6.7		5.8			ns
	32x1	$T_{DOT}$		8.2		7.2		6.2			ns
<b>Read During Write, Clocking Data into Flip-Flop</b>											
WE setup time before clock K	16x2	$T_{WCK}$	7.1		6.2		5.5				ns
	32x1	$T_{WCKT}$	9.2		8.1		7.0				ns
Data setup time before clock K	16x2	$T_{DCK}$	5.9		5.2		4.6				ns
	32x1	$T_{DCKT}$	8.4		7.4		6.4				ns
<b>Preliminary</b>											

Note: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.

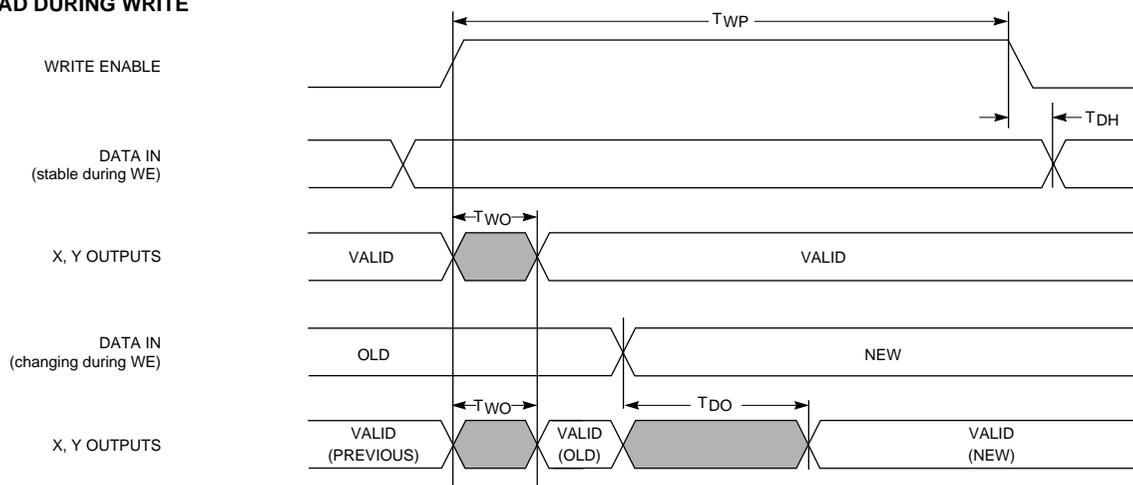
## XC4000EX CLB RAM Asynchronous (Level-Sensitive) Timing Characteristics



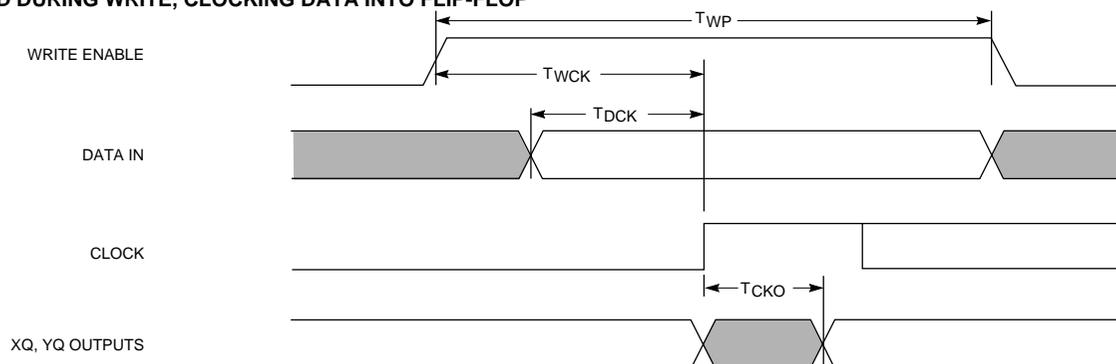
### READ, CLOCKING DATA INTO FLIP-FLOP



### READ DURING WRITE



### READ DURING WRITE, CLOCKING DATA INTO FLIP-FLOP



X2640

## XC4000EX Pin-to-Pin Output Parameter Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000EX devices unless otherwise noted.

### XC4000EX Output Flip-Flop, Clock to Out

			Speed Grade			-1	Units
Description	Symbol	Device	-4 Max	-3 Max	-2 Max	Max	
Global Low Skew Clock to TTL Output (fast) using OFF	T <sub>ICKOF</sub>	XC4028EX	16.6	13.7	12.4		ns
		XC4036EX	17.2	14.1	13.1		ns
Global Early Clock to TTL Output (fast) using OFF	T <sub>ICKEOF</sub>	XC4028EX	13.1	10.6	10.2		ns
		XC4036EX	13.3	10.8	10.4		ns

OFF = Output Flip Flop

**Preliminary**

### XC4000EX Output MUX, Clock to Out

			Speed Grade			-1	Units
Description	Symbol	Device	-4 Max	-3 Max	-2 Max	Max	
Global Low Skew Clock to TTL Output (fast) using OMUX	T <sub>PFPF</sub>	XC4028EX	15.9	13.1	11.8		ns
		XC4036EX	16.5	13.5	12.5		ns
Global Early Clock to TTL Output (fast) using OMUX	T <sub>PEFPF</sub>	XC4028EX	12.4	10.0	9.6		ns
		XC4036EX	12.6	10.2	9.8		ns

OMUX = Output MUX

**Preliminary**

Notes: Listed above are representative values where one global clock input drives one vertical clock line in each accessible column, and where all accessible IOB and CLB flip-flops are clocked by the global clock net. Output timing is measured at TTL threshold with 35 pF external capacitive load. Set-up time is measured with the fastest route and the lightest load. Hold time is measured using the farthest distance and a reference load of one clock pin per two IOBs. Use the static timing analyzer to determine the setup and hold times under given design conditions.

### XC4000EX Output Level and Slew Rate Adjustments

The following table must be used to adjust output parameters and output switching characteristics.

			Speed Grade			-1	Units
Description	Symbol	Device	-4 Max	-3 Max	-2 Max	Max	
For TTL output FAST add	T <sub>TTLOF</sub>	All Devices	0	0	0		ns
For TTL output SLOW add	T <sub>TTLO</sub>	All Devices	2.9	2.4	2.4		ns
For CMOS FAST output add	T <sub>CMOSOF</sub>	All Devices	1.0	0.8	0.8		ns
For CMOS SLOW output add	T <sub>CMOSO</sub>	All Devices	3.6	3.0	3.0		ns

**Preliminary**

## XC4000EX Pin-to-Pin Input Parameter Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000EX devices unless otherwise noted

### XC4000EX Global Low Skew Clock, Set-Up and Hold

			Speed Grade			-1	Units
Description	Symbol	Device	-4	-3	-2	Min	
Input Setup Time, using Global Low Skew clock and IFF (full delay)	T <sub>PSD</sub>	XC4028EX	8.0	6.8	6.8		ns
		XC4036EX	8.0	6.8	6.8		ns
Input Hold Time, using Global Low Skew clock and IFF (full delay)	T <sub>PHD</sub>	XC4028EX	0	0	0		ns
		XC4036EX	0	0	0		ns
IFF = Flip-Flop or Latch			<b>Preliminary</b>				

### XC4000EX Global Early Clock, Set-Up and Hold for IFF

			Speed Grade			-1	Units
Description	Symbol	Device	-4	-3	-2	Min	
Input Setup Time, using Global Early clock and IFF (partial delay)	T <sub>PSEP</sub>	XC4028EX	6.5	5.4	5.4		ns
		XC4036EX	6.5	5.4	5.4		ns
Input Hold Time, using Global Early clock and IFF (partial delay)	T <sub>PHEP</sub>	XC4028EX	0	0	0		ns
		XC4036EX	0	0	0		ns
IFF = Flip-Flop or Latch			<b>Preliminary</b>				

Note: Set-up parameters are for BUFGE #s 3, 4, 7 and 8. Add 1.6 ns for BUFGE #s 1, 2, 5 and 6.

### XC4000EX Global Early Clock, Set-Up and Hold for FCL

			Speed Grade			-1	Units
Description	Symbol	Device	-4	-3	-2	Min	
Input Setup Time, using Global Early clock and FCL (partial delay)	T <sub>PFSEP</sub>	XC4028EX	3.4	3.4	3.4		ns
		XC4036EX	4.4	4.2	4.2		ns
Input Hold Time, using Global Early clock and FCL (partial delay)	T <sub>PFHEP</sub>	XC4028EX	0	0	0		ns
		XC4036EX	0	0	0		ns
FCL = Fast Capture Latch			<b>Preliminary</b>				

Notes: For CMOS output levels, see the Output Level and Slew Rate Adjustments tables on page 10.

Setup time is measured with the fastest route and the lightest load. Use the static timing analyzer to determine the setup time under given design conditions. Hold time is measured using the farthest distance and a reference load of one clock pin per two IOBs. Use the static timing analyzer to determine the setup and hold times under given design conditions.

Note: Set-up parameters are for BUFGE #s 3, 4, 7 and 8. Add 1.2 ns for BUFGE #s 1, 2, 5 and 6.

### XC4000EX Input Threshold and Slew Rate Adjustments

The following table must be used to adjust input parameters and input switching characteristics.

			Speed Grade			-1	Units
Description	Symbol	Device	-4	-3	-2	Max	
For TTL input add	T <sub>TTLI</sub>	All Devices	0	0	0		ns
For CMOS input add	T <sub>CMOSI</sub>	All Devices	0.3	0.2	0.2		ns
			<b>Preliminary</b>				

### XC4000EX IOB Input Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted.

Description	Speed Grade		-4	-3	-2	-1	Units
	Symbol	Device	Min	Min	Min	Min	
<b>Clocks</b>							
Delay from FCL enable (OK) active edge to IFF clock (IK) active edge	T <sub>OKIK</sub>	All devices	3.2	2.6	2.6		ns
<b>Propagation Delays</b>			<b>Max</b>	<b>Max</b>	<b>Max</b>	<b>Max</b>	
Pad to I1, I2	T <sub>PID</sub>	All devices	2.2	1.9	1.8		ns
Pad to I1, I2 via transparent input latch, no delay	T <sub>PLI</sub>	All devices	3.8	3.2	3.0		ns
Pad to I1, I2 via transparent input latch, partial delay	T <sub>PPLI</sub>	XC4028EX	13.3	11.1	10.9		ns
		XC4036EX	14.5	12.1	11.9		ns
Pad to I1, I2 via transparent input latch, full delay	T <sub>PDLI</sub>	XC4028EX	18.2	15.2	14.9		ns
		XC4036EX	19.4	16.2	15.9		ns
Pad to I1, I2 via transparent FCL and input latch, no delay	T <sub>PPFLI</sub>	All devices	5.3	4.4	4.2		ns
Pad to I1, I2 via transparent FCL and input latch, partial delay	T <sub>PPFLI</sub>	XC4028EX	13.6	11.3	11.1		ns
		XC4036EX	14.8	12.3	12.1		ns
<b>Propagation Delays</b>							
Clock (IK) to I1, I2 (flip-flop)	T <sub>IKRI</sub>	All devices	3.0	2.5	2.4		ns
Clock (IK) to I1, I2 (latch enable, active Low)	T <sub>IKLI</sub>	All devices	3.2	2.7	2.6		ns
FCL Enable (OK) active edge to I1, I2 (via transparent standard input latch)	T <sub>OKLI</sub>	All devices	6.2	5.2	5.0		ns
<b>Global Set/Reset</b>							
Minimum GSR Pulse Width	T <sub>MRW</sub>	All devices	13.0	11.5	11.5		ns
Delay from GSR input to any Q	T <sub>RRI</sub>	XC4028EX	22.8	19.0	19.0		ns
Delay from GSR input to any Q	T <sub>RRI</sub>	XC4036EX	24.0	21.0	21.0		ns

FCL = Fast Capture Latch, IFF = Input Flip-Flop or Latch

**Preliminary**

Notes: For CMOS output levels, see the Output Level and Slew Rate Adjustments table on page 10.  
 For setup and hold times with respect to the clock input pin, see the Global Low Skew Clock and Global Early Clock Set-up and Hold tables on page 11.

## XC4000EX IOB Input Switching Characteristic Guidelines (Continued)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000EX devices unless otherwise noted.

Description	Speed Grade		-4	-3	-2	-1	Units
	Symbol	Device	Min	Min	Min	Min	
<b>Setup Times</b>							
Pad to Clock (IK), no delay	T <sub>PICK</sub>	All devices	2.5	2.0	2.0		ns
Pad to Clock (IK), partial delay	T <sub>PICKP</sub>	XC4028EX	10.8	9.0	9.0		ns
		XC4036EX	12.0	10.0	10.0		ns
Pad to Clock (IK), full delay	T <sub>PICKD</sub>	XC4028EX	15.7	13.1	13.1		ns
		XC4036EX	16.9	14.1	14.1		ns
Pad to Clock (IK), via transparent Fast Capture Latch, no delay	T <sub>PICKF</sub>	All devices	3.9	3.3	3.3		ns
Pad to Clock (IK), via transparent Fast Capture Latch, partial delay	T <sub>PICKFP</sub>	XC4028EX	12.3	10.2	10.2		ns
		XC4036EX	13.5	11.2	11.2		ns
Pad to Fast Capture Latch Enable (OK), no delay	T <sub>POCK</sub>	All devices	0.8	0.7	0.7		ns
Pad to Fast Capture Latch Enable (OK), partial delay	T <sub>POCKP</sub>	XC4028EX	9.1	7.6	7.6		ns
		XC4036EX	10.3	8.6	8.6		ns
<b>Setup Times (TTL or CMOS Inputs)</b>							
Clock Enable (EC) to Clock (IK)	T <sub>ECIK</sub>	All devices	0.3	0.2	0.2		ns
<b>Hold Times</b>							
Pad to Clock (IK), no delay partial delay full delay	T <sub>IKPI</sub>	All devices	0	0	0		ns
	T <sub>IKPIP</sub>	All devices	0	0	0		ns
	T <sub>IKPID</sub>	All devices	0	0	0		ns
Pad to Clock (IK) via transparent Fast Capture Latch, no delay partial delay full delay	T <sub>IKFPI</sub>	All devices	0	0	0		ns
	T <sub>IKFPIP</sub>	All devices	0	0	0		ns
	T <sub>IKFPID</sub>	All devices	0	0	0		ns
Clock Enable (EC) to Clock (IK), no delay partial delay full delay	T <sub>IKEC</sub>	All devices	0	0	0		ns
	T <sub>IKECP</sub>	All devices	0	0	0		ns
	T <sub>IKECD</sub>	All devices	0	0	0		ns
Pad to Fast Capture Latch Enable (OK), no delay partial delay	T <sub>OKPI</sub>	All devices	0	0	0		ns
	T <sub>OKPIP</sub>	All devices	0	0	0		ns
			<b>Preliminary</b>				

Notes: For CMOS output levels, see the Output Level and Slew Rate Adjustments table on page 10.  
For setup and hold times with respect to the clock input pin, see the Global Low Skew Clock and Global Early Clock Set-up and Hold tables on page 11.

### XC4000EX IOB Output Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). For Propagation Delays, slew-rate = fast unless otherwise noted. Values apply to all XC4000EX devices unless otherwise noted.

		Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Propagation Delays</b>												
Clock (OK) to Pad	T <sub>OKPOF</sub>		7.4		6.2		6.0					ns
Output (O) to Pad	T <sub>OPF</sub>		6.2		5.2		5.0					ns
3-state to Pad hi-Z (slew-rate independent)	T <sub>TSHZ</sub>		4.9		4.1		4.1					ns
3-state to Pad active and valid	T <sub>TSONF</sub>		6.2		5.2		5.0					ns
Output MUX Select (OK) to Pad	T <sub>OKFPF</sub>		6.7		5.6		5.4					ns
Fast Path Output MUX Input (EC) to Pad	T <sub>CEFPF</sub>		6.2		5.1		5.0					ns
Slowest Path Output MUX Input (O) to Pad	T <sub>OFFP</sub>		7.3		6.0		5.9					ns
<b>Setup and Hold Times</b>												
Output (O) to clock (OK) setup time	T <sub>OOK</sub>	0.6		0.5		0.5						ns
Output (O) to clock (OK) hold time	T <sub>OKO</sub>	0		0		0						ns
Clock Enable (EC) to clock (OK) setup	T <sub>ECOK</sub>	0		0		0						ns
Clock Enable (EC) to clock (OK) hold	T <sub>OKEC</sub>	0		0		0						ns
<b>Clock</b>												
Clock High	T <sub>CH</sub>	3.5		3.0		3.0						ns
Clock Low	T <sub>CL</sub>	3.5		3.0		3.0						ns
<b>Global Set/Reset</b>												
Minimum GSR pulse width	T <sub>MRW</sub>	13.0		11.5		11.5						ns
Delay from GSR input to any Pad (XC4028EX)	T <sub>RPO</sub>	<b>30.2</b>		<b>25.2</b>		<b>25.0</b>						ns
Delay from GSR input to any Pad (XC4036EX)	T <sub>RPO</sub>	<b>31.4</b>		<b>27.2</b>		<b>27.0</b>						ns
<b>Preliminary</b>												

Notes: Output timing is measured at TTL threshold, with 35pF external capacitive loads.  
 For CMOS output levels, see the Output Level and Slew Rate Adjustments table on page 10

## XC4000E Switching Characteristics

### Definition of Terms

In the following tables, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

**Advance:** Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or device families. Use as estimates, not for production.

**Preliminary:** Based on preliminary characterization. Further changes are not expected.

**Unmarked:** Specifications not identified as either Advance or Preliminary are to be considered Final.<sup>1</sup>

### XC4000E Absolute Maximum Ratings

Symbol	Description	Value	Units	
$V_{CC}$	Supply voltage relative to GND	-0.5 to +7.0	V	
$V_{IN}$	Input voltage relative to GND (Note 1)	-0.5 to $V_{CC} + 0.5$	V	
$V_{TS}$	Voltage applied to 3-state output (Note 1)	-0.5 to $V_{CC} + 0.5$	V	
$T_{STG}$	Storage temperature (ambient)	-65 to +150	°C	
$T_{SOL}$	Maximum soldering temperature (10 s @ 1/16 in. = 1.5 mm)	+260	°C	
$T_J$	Junction temperature	Ceramic packages	+150	°C
		Plastic packages	+125	°C

Note 1: Maximum DC overshoot or undershoot above  $V_{CC}$  or below GND must be limited to either 0.5 V or 10 mA, whichever is easier to achieve. During transitions, the device pins may undershoot to -2.0 V or overshoot to  $V_{CC} + 2.0$  V, provided this over- or undershoot lasts less than 20 ns.

Note 2: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.

### XC4000E Recommended Operating Conditions

Symbol	Description	Min	Max	Units	
$V_{CC}$	Supply voltage relative to GND, $T_J = -0$ °C to +85°C	Commercial	4.75	5.25	V
	Supply voltage relative to GND, $T_J = -40$ °C to +100°C	Industrial	4.5	5.5	V
	Supply voltage relative to GND, $T_C = -55$ °C to +125°C	Military	4.5	5.5	V
$V_{IH}$	High-level input voltage	TTL inputs	2.0	$V_{CC}$	V
		CMOS inputs	70%	100%	$V_{CC}$
$V_{IL}$	Low-level input voltage	TTL inputs	0	0.8	V
		CMOS inputs	0	20%	$V_{CC}$
$T_{IN}$	Input signal transition time		250	ns	

Note: At junction temperatures above those listed as Recommended Operating Conditions, all delay parameters increase by 0.35% per °C.

Input and output Measurement thresholds are: 1.5V for TTL and 2.5V for CMOS.

1. Notwithstanding the definition of the above terms, all specifications are subject to change without notice.

### XC4000E DC Characteristics Over Operating Conditions

Symbol	Description		Min	Max	Units
V <sub>OH</sub>	High-level output voltage @ I <sub>OH</sub> = -4.0mA, V <sub>CC</sub> min	TTL outputs	2.4		V
	High-level output voltage @ I <sub>OH</sub> = -1.0mA, V <sub>CC</sub> min	CMOS outputs	V <sub>CC</sub> -0.5		V
V <sub>OL</sub>	Low-level output voltage @ I <sub>OL</sub> = 12.0mA, V <sub>CC</sub> min (Note 1)	TTL outputs		0.4	V
		CMOS outputs		0.4	V
I <sub>CCO</sub>	Quiescent FPGA supply current (Note 2)	Commercial		3.0	mA
		Industrial		6.0	mA
		Military		6.0	mA
I <sub>L</sub>	Input or output leakage current		-10	+10	μA
C <sub>IN</sub>	Input capacitance (sample tested)	PQFP and MQFP packages		10	pF
		Other packages		16	pF
I <sub>RIN</sub> *	Pad pull-up (when selected) @ V <sub>IN</sub> = 0V (sample tested)		-0.02	-0.25	mA
I <sub>RLL</sub> *	Horizontal Longline pull-up (when selected) @ logic Low		0.2	2.5	mA

Note 1: With 50% of the outputs simultaneously sinking 12mA, up to a maximum of 64 pins.

Note 2: With no output current loads, no active input or Longline pull-up resistors, all package pins at V<sub>CC</sub> or GND, and the FPGA configured with a MakeBits Tie option.

\* Characterized Only.

### XC4000E Global Buffer Switching Characteristic Guidelines

Testing of the switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values where one global clock input drives one vertical clock line in each accessible column, and where all accessible IOB and CLB flip-flops are clocked by the global clock net.

When fewer vertical clock lines are connected, the clock distribution is faster; when multiple clock lines per column are driven from the same global clock, the delay is longer. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature)

		Speed Grade		-4	-3	-2	-1	
Description	Symbol	Device	Max	Max	Max	Max	Max	Units
From pad through Primary buffer, to any clock K	T <sub>PG</sub>	XC4003E	7.0	4.7	4.0	3.5	ns	
		XC4005E	7.0	4.7	4.3	3.8	ns	
		XC4006E	7.5	5.3	5.2	4.6	ns	
		XC4008E	8.0	6.1	5.2	4.6	ns	
		XC4010E	11.0	6.3	5.4	4.8	ns	
		XC4013E	11.5	6.8	5.8	5.2	ns	
		XC4020E	12.0	7.0	6.4	6.0	ns	
		XC4025E	12.5	7.2	6.9	–	ns	
From pad through Secondary buffer, to any clock K	T <sub>SG</sub>	XC4003E	7.5	5.2	4.4	4.0	ns	
		XC4005E	7.5	5.2	4.7	4.3	ns	
		XC4006E	8.0	5.8	5.6	5.1	ns	
		XC4008E	8.5	6.6	5.6	5.1	ns	
		XC4010E	11.5	6.8	5.8	5.3	ns	
		XC4013E	12.0	7.3	6.2	5.7	ns	
		XC4020E	12.5	7.5	6.7	6.5	ns	
		XC4025E	13.0	7.7	7.2	–	ns	

Preliminary

## XC4000E Horizontal Longline Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

The following guidelines reflect worst-case values over the recommended operating conditions.

Description	Speed Grade		-4	-3	-2	-1	Units
	Symbol	Device	Max	Max	Max	Max	
<b>TBUF driving a Horizontal Longline (LL):</b>							
I going High or Low to LL going High or Low, while T is Low. Buffer is constantly active. (Note1)	T <sub>IO1</sub>	XC4003E	5.0	4.2	3.4	2.9	ns
		XC4005E	5.0	5.0	4.0	3.4	ns
		XC4006E	6.0	5.9	4.7	4.0	ns
		XC4008E	7.0	6.3	5.0	4.3	ns
		XC4010E	8.0	6.4	5.1	4.4	ns
		XC4013E	9.0	7.2	5.7	4.9	ns
		XC4020E	10.0	8.2	7.3	5.6	ns
		XC4025E	11.0	9.1	7.3	–	ns
I going Low to LL going from resistive pull-up High to active Low. TBUF configured as open-drain. (Note1)	T <sub>IO2</sub>	XC4003E	5.0	4.2	3.6	3.1	ns
		XC4005E	6.0	5.3	4.5	3.8	ns
		XC4006E	7.8	6.4	5.4	4.6	ns
		XC4008E	8.1	6.8	5.8	4.9	ns
		XC4010E	10.5	6.9	5.9	5.0	ns
		XC4013E	11.0	7.7	6.5	5.5	ns
		XC4020E	12.0	8.7	8.7	7.4	ns
		XC4025E	12.0	9.6	9.6	–	ns
T going Low to LL going from resistive pull-up or floating High to active Low. TBUF configured as open-drain or active buffer with I = Low. (Note1)	T <sub>ON</sub>	XC4003E	5.5	4.6	3.9	3.5	ns
		XC4005E	7.0	6.0	5.7	4.7	ns
		XC4006E	7.5	6.7	5.7	4.9	ns
		XC4008E	8.0	7.1	6.0	5.2	ns
		XC4010E	8.5	7.3	6.2	5.4	ns
		XC4013E	8.7	7.5	7.0	6.2	ns
		XC4020E	11.0	8.4	7.1	6.3	ns
		XC4025E	11.0	8.4	7.1	–	ns
T going High to TBUF going inactive, not driving LL	T <sub>OFF</sub>	All devices	1.8	1.5	1.3	1.1	ns
T going High to LL going from Low to High, pulled up by a single resistor. (Note 1)	T <sub>PUS</sub>	XC4003E	20.0	14.0	14.0	12.0	ns
		XC4005E	23.0	16.0	16.0	14.0	ns
		XC4006E	25.0	18.0	18.0	16.0	ns
		XC4008E	27.0	20.0	20.0	16.0	ns
		XC4010E	29.0	22.0	22.0	18.0	ns
		XC4013E	32.0	26.0	26.0	21.0	ns
		XC4020E	35.0	32.5	32.5	26.0	ns
		XC4025E	42.0	39.1	39.1	–	ns
T going High to LL going from Low to High, pulled up by two resistors. (Note1)	T <sub>PUF</sub>	XC4003E	9.0	7.0	6.0	5.4	ns
		XC4005E	10.0	8.0	6.8	5.8	ns
		XC4006E	11.5	9.0	7.7	6.5	ns
		XC4008E	12.5	10.0	8.5	7.5	ns
		XC4010E	13.5	11.0	9.4	8.0	ns
		XC4013E	15.0	13.0	11.7	9.4	ns
		XC4020E	16.0	14.8	14.8	10.5	ns
		XC4025E	18.0	16.5	16.5	–	ns

Preliminary

Note 1: These values include a minimum load. Use the static timing analyzer to determine the delay for each destination.

### XC4000E Wide Decoder Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

The following guidelines reflect worst-case values over the recommended operating conditions.

		Speed Grade	-4	-3	-2	-1	
Description	Symbol	Device	Max	Max	Max	Max	Units
Full length, both pull-ups, inputs from IOB I-pins	T <sub>WAF</sub>	XC4003E	9.2	5.0	5.0	4.3	ns
		XC4005E	9.5	6.0	6.0	5.1	ns
		XC4006E	12.0	7.0	7.0	6.0	ns
		XC4008E	12.5	8.0	8.0	6.5	ns
		XC4010E	15.0	9.0	9.0	7.5	ns
		XC4013E	16.0	11.0	11.0	8.6	ns
		XC4020E	17.0	13.9	13.9	10.1	ns
		XC4025E	18.0	16.9	16.9	–	ns
Full length, both pull-ups, inputs from internal logic	T <sub>WAF<sub>L</sub></sub>	XC4003E	12.0	7.0	7.0	5.5	ns
		XC4005E	12.5	8.0	8.0	6.4	ns
		XC4006E	14.0	9.0	9.0	7.0	ns
		XC4008E	16.0	10.0	10.0	7.5	ns
		XC4010E	18.0	11.0	11.0	8.5	ns
		XC4013E	19.0	13.0	13.0	10.0	ns
		XC4020E	20.0	15.5	15.5	11.8	ns
		XC4025E	21.0	18.9	18.9	–	ns
Half length, one pull-up, inputs from IOB I-pins	T <sub>WAO</sub>	XC4003E	10.5	6.0	6.0	5.1	ns
		XC4005E	10.5	7.0	7.0	6.0	ns
		XC4006E	13.5	8.0	8.0	6.5	ns
		XC4008E	14.0	9.0	9.0	7.0	ns
		XC4010E	16.0	10.0	10.0	7.5	ns
		XC4013E	17.0	12.0	12.0	10.0	ns
		XC4020E	18.0	15.0	15.0	11.8	ns
		XC4025E	19.0	17.6	17.6	–	ns
Half length, one pull-up, inputs from internal logic	T <sub>WAO<sub>L</sub></sub>	XC4003E	12.0	8.0	8.0	6.0	ns
		XC4005E	12.5	9.0	9.0	7.0	ns
		XC4006E	14.0	10.0	10.0	7.6	ns
		XC4008E	16.0	11.0	11.0	8.4	ns
		XC4010E	18.0	12.0	12.0	9.2	ns
		XC4013E	19.0	14.0	14.0	10.8	ns
		XC4020E	20.0	16.8	16.8	12.6	ns
		XC4025E	21.0	19.6	19.6	–	ns

**Preliminary**

Notes: These delays are specified from the decoder input to the decoder output. Fewer than the specified number of pullup resistors can be used, if desired. Using fewer pullups reduces power consumption but increases delays. Use the static timing analyzer to determine delays if fewer pullups are used.

## XC4000E CLB Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Combinatorial Delays</b>										
F/G inputs to X/Y outputs	T <sub>ILO</sub>		2.7		2.0		1.6		1.3	ns
F/G inputs via H to X/Y outputs	T <sub>IHO</sub>		4.7		4.3		2.7		2.2	ns
C inputs via SR through H to X/Y outputs	T <sub>HH0O</sub>		4.1		3.3		2.4		1.9	ns
C inputs via H to X/Y outputs	T <sub>HH1O</sub>		3.7		3.6		2.2		1.6	ns
C inputs via DIN through H to X/Y outputs	T <sub>HH2O</sub>		4.5		3.6		2.6		1.9	ns
<b>CLB Fast Carry Logic</b>										
Operand inputs (F1, F2, G1, G4) to COUT	T <sub>OPCY</sub>		3.2		2.6		2.1		1.7	ns
Add/Subtract input (F3) to COUT	T <sub>ASCY</sub>		5.5		4.4		3.7		2.5	ns
Initialization inputs (F1, F3) to COUT	T <sub>INCY</sub>		1.7		1.7		1.4		1.2	ns
CIN through function generators to X/Y outputs	T <sub>SUM</sub>		3.8		3.3		2.6		1.8	ns
CIN to COUT, bypass function generators	T <sub>BYP</sub>		1.0		0.7		0.6		0.5	ns
<b>Sequential Delays</b>										
Clock K to outputs Q	T <sub>CKO</sub>		3.7		2.8		2.8		1.9	ns
<b>Setup Time before Clock K</b>										
F/G inputs	T <sub>ICK</sub>	4.0		3.0		2.4		1.8		ns
F/G inputs via H	T <sub>IHCK</sub>	6.1		4.6		3.9		2.8		ns
C inputs via H0 through H	T <sub>HH0CK</sub>	4.5		3.6		3.5		2.4		ns
C inputs via H1 through H	T <sub>HH1CK</sub>	5.0		4.1		3.3		2.1		ns
C inputs via H2 through H	T <sub>HH2CK</sub>	4.8		3.8		3.7		2.5		ns
C inputs via DIN	T <sub>DICK</sub>	3.0		2.4		2.0		1.0		ns
C inputs via EC	T <sub>ECCK</sub>	4.0		3.0		2.6		2.0		ns
C inputs via S/R, going Low (inactive)	T <sub>RCK</sub>	4.2		4.0		4.0		1.5		ns
C <sub>IN</sub> input via F/G	T <sub>CCK</sub>	2.5		2.1						ns
C <sub>IN</sub> input via F/G and H	T <sub>CHCK</sub>	4.2		3.5						ns

Preliminary

### XC4000E CLB Switching Characteristic Guidelines (continued)

Testing of the switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are not measured directly. They are derived from benchmark timing patterns that are taken at device introduction, prior to any process improvements. For more detailed, more precise, and more up-to-date information, use the values provided by the XACT timing calculator and used in the simulator. These values can be printed in tabular format by running LCA2XNF -S.

The following guidelines reflect worst-case values over the recommended operating conditions. They are expressed in units of nanoseconds and apply to all XC4000E devices unless otherwise noted.

Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Hold Time after Clock K</b>										
F/G inputs	T <sub>CKI</sub>	0		0		0		0		ns
F/G inputs via H	T <sub>CKIH</sub>	0		0		0		0		ns
C inputs via H0 through H	T <sub>CKHH0</sub>	0		0		0		0		ns
C inputs via H1 through H	T <sub>CKHH1</sub>	0		0		0		0		ns
C inputs via H2 through H	T <sub>CKHH2</sub>	0		0		0		0		ns
C inputs via DIN	T <sub>CKDI</sub>	0		0		0		0		ns
C inputs via EC	T <sub>CKEC</sub>	0		0		0		0		ns
C inputs via SR, going Low (inactive)	T <sub>CKR</sub>	0		0		0		0		ns
<b>Clock</b>										
Clock High time	T <sub>CH</sub>	4.5		4.0		4.0		3.0		ns
Clock Low time	T <sub>CL</sub>	4.5		4.0		4.0		3.0		ns
<b>Set/Reset Direct</b>										
Width (High)	T <sub>RPW</sub>	5.5		4.0		4.0		3.0		ns
Delay from C inputs via S/R, going High to Q	T <sub>RIO</sub>		6.5		4.0		4.0		3.0	ns
<b>Master Set/Reset (Note 1)</b>										
Width (High or Low)	T <sub>MRW</sub>	13.0		11.5		11.5		10.0		ns
Delay from Global Set/Reset net to Q	T <sub>MRQ</sub>		23.0		18.7		17.4		15.0	ns
Global Set/Reset inactive to first active clock K edge	T <sub>MRK</sub>									
Toggle Frequency (Note 2)	F <sub>TOG</sub>		111		125		125		166	MHz
<b>Preliminary</b>										

Note 1: Timing is based on the XC4005E. For other devices see the XACT timing calculator.  
 Note 2: Export Control Max. flip-flop toggle rate.

## XC4000E CLB Edge-Triggered (Synchronous) RAM Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

Single Port RAM	Speed Grade		-4		-3		-2		-1		Units
	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time (clock K period)	16x2	$T_{WCS}$	15.0		14.4		11.6		8.0		ns
	32x1	$T_{WCTS}$	15.0		14.4		11.6		8.0		ns
Clock K pulse width (active edge)	16x2	$T_{WPS}$	7.5	1 ms	7.2	1 ms	5.8	1 ms	4.0		ns
	32x1	$T_{WPTS}$	7.5	1 ms	7.2	1 ms	5.8	1 ms	4.0		ns
Address setup time before clock K	16x2	$T_{ASS}$	2.8		2.4		2.0		1.5		ns
	32x1	$T_{ASTS}$	2.8		2.4		2.0		1.5		ns
Address hold time after clock K	16x2	$T_{AHS}$	0		0		0		0		ns
	32x1	$T_{AHTS}$	0		0		0		0		ns
DIN setup time before clock K	16x2	$T_{DSS}$	3.5		3.2		2.7		1.5		ns
	32x1	$T_{DSTS}$	2.5		1.9		1.7		1.5		ns
DIN hold time after clock K	16x2	$T_{DHS}$	0		0		0		0		ns
	32x1	$T_{DHTS}$	0		0		0		0		ns
WE setup time before clock K	16x2	$T_{WSS}$	2.2		2.0		1.6		1.5		ns
	32x1	$T_{WSTS}$	2.2		2.0		1.6		1.5		ns
WE hold time after clock K	16x2	$T_{WHS}$	0		0		0		0		ns
	32x1	$T_{WHTS}$	0		0		0		0		ns
Data valid after clock K	16x2	$T_{WOS}$		10.3		8.8		7.9		6.5	ns
	32x1	$T_{WOTS}$		11.6		10.3		9.3		7.0	ns

Preliminary

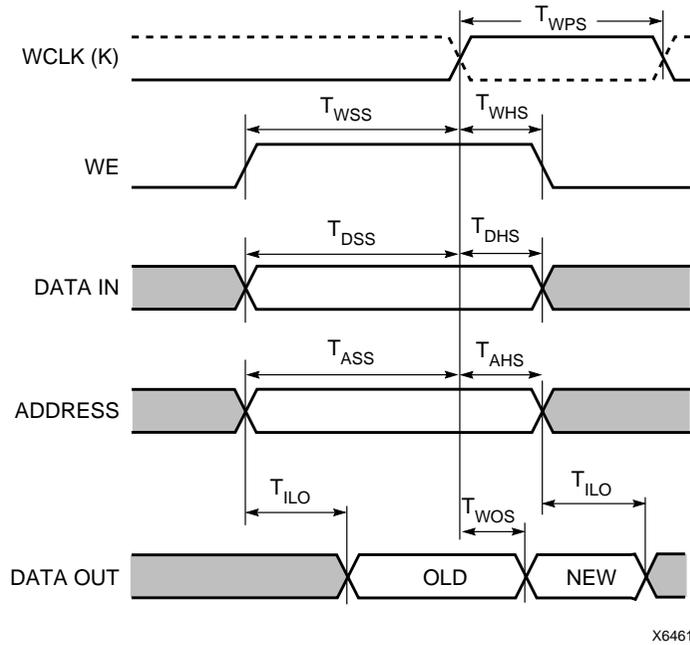
Notes: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.  
Applicable Read timing specifications are identical to Level-Sensitive Read timing.

Dual-Port RAM	Speed Grade		-4		-3		-2		-1		Units
	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time (clock K period)	16x1	$T_{WCDS}$	15.0		9.0		11.6		8.0		ns
Clock K pulse width (active edge)	16x1	$T_{WPDS}$		1 ms	4.5	1 ms	5.8	1 ms	4.0		ns
Address setup time before clock K	16x1	$T_{ASDS}$	7.5		2.5		2.1		1.5		ns
Address hold time after clock K	16x1	$T_{AHDS}$	2.8		0		0		0		ns
DIN setup time before clock K	16x1	$T_{DSDS}$	0		2.5		1.6		1.5		ns
DIN hold time after clock K	16x1	$T_{DHDS}$	2.2		0		0		0		ns
WE setup time before clock K	16x1	$T_{WSDS}$	0		1.8		1.6		1.5		ns
WE hold time after clock K	16x1	$T_{WHDS}$	2.2		0		0		0		ns
Data valid after clock K	16x1	$T_{WODS}$	0.3	10.0		7.8		7.0		6.5	ns

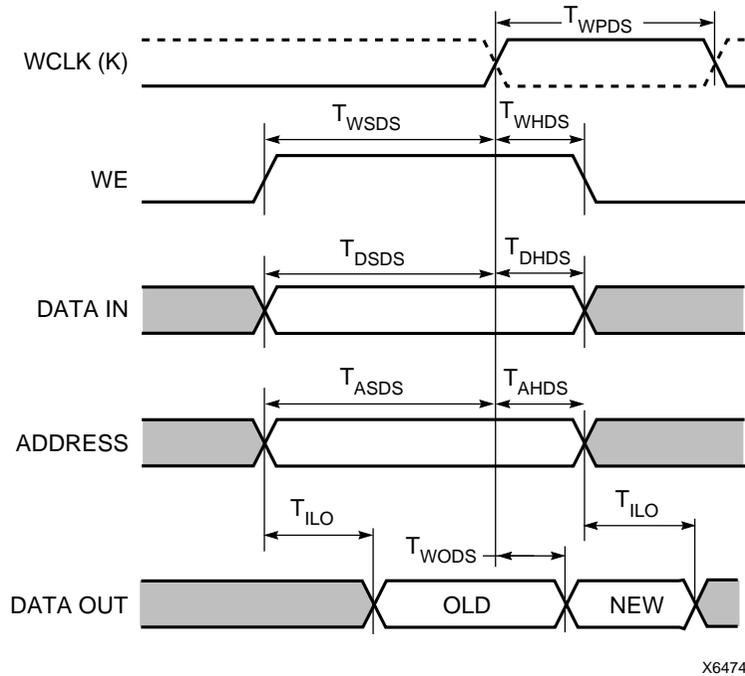
Preliminary

Note: Applicable Read timing specifications are identical to Level-Sensitive Read timing.

**XC4000E CLB RAM Synchronous (Edge-Triggered) Write Timing**



**XC4000E CLB Dual-Port RAM Synchronous (Edge-Triggered) Write Timing**



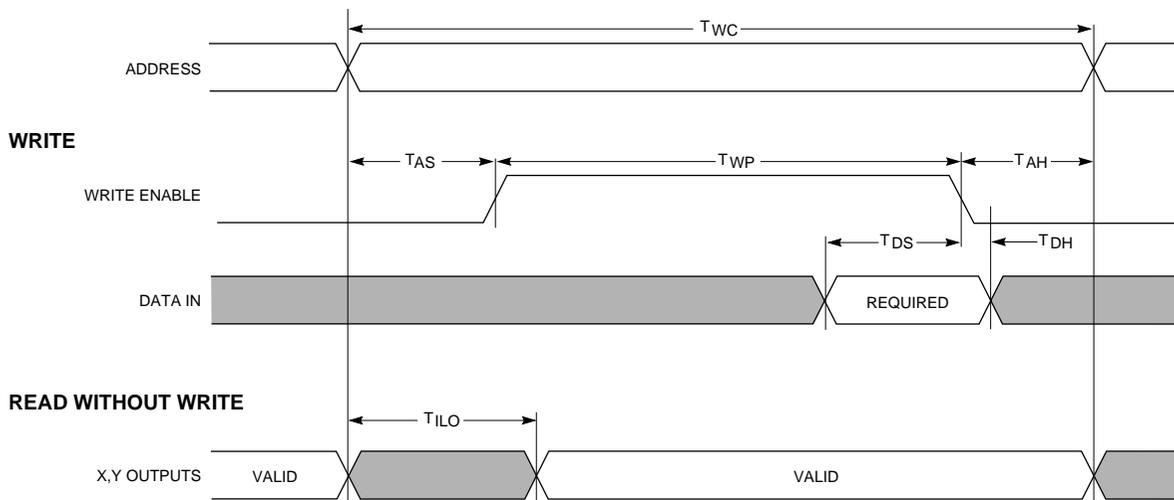
## XC4000E CLB Level-Sensitive RAM Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

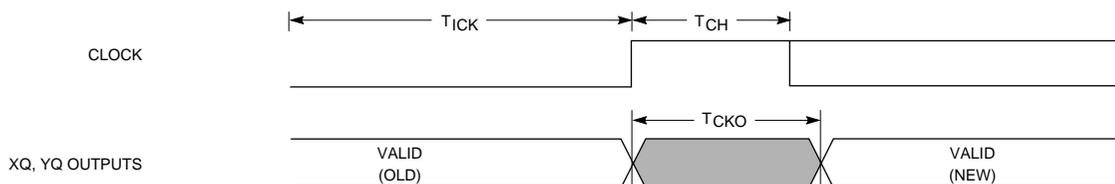
Speed Grade			-4		-3		-2		-1		Units
Description	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Write Operation</b>											
Address write cycle time	16x2	$T_{WC}$	8.0		8.0		8.0		8.0		ns
	32x1	$T_{WCT}$	8.0		8.0		8.0		8.0		ns
Write Enable pulse width (High)	16x2	$T_{WP}$	4.0		4.0		4.0		4.0		ns
	32x1	$T_{WPT}$	4.0		4.0		4.0		4.0		ns
Address setup time before WE	16x2	$T_{AS}$	2.0		2.0		2.0		2.0		ns
	32x1	$T_{AST}$	2.0		2.0		2.0		2.0		ns
Address hold time after end of WE	16x2	$T_{AH}$	2.5		2.0		2.0		2.0		ns
	32x1	$T_{AHT}$	2.0		2.0		2.0		2.0		ns
DIN setup time before end of WE	16x2	$T_{DS}$	4.0		2.2		0.8		0.8		ns
	32x1	$T_{DST}$	5.0		2.2		0.8		0.8		ns
DIN hold time after end of WE	16x2	$T_{DH}$	2.0		2.0		2.0		2.0		ns
	32x1	$T_{DHT}$	2.0		2.0		2.0		2.0		ns
<b>Read Operation</b>											
Address read cycle time	16x2	$T_{RC}$	4.5		3.1		2.6		2.6		ns
	32x1	$T_{RCT}$	6.5		5.5		3.8		3.8		ns
Data valid after address change (no Write Enable)	16x2 32x1	$T_{ILO}$		2.7		1.8		1.6		1.6	ns
		$T_{IHO}$		4.7		3.2		2.7		2.7	ns
<b>Read Operation, Clocking Data into Flip-Flop</b>											
Address setup time before clock K	16x2	$T_{ICK}$	4.0		3.0		2.4		2.4		ns
	32x1	$T_{IHCK}$	6.1		4.6		3.9		3.9		ns
<b>Read During Write</b>											
Data valid after WE goes active (DIN stable before WE)	16x2 32x1	$T_{WO}$		10.0		6.0		4.9		4.9	ns
		$T_{WOT}$		12.0		7.3		5.6		5.6	ns
Data valid after DIN (DIN changes during WE)	16x2 32x1	$T_{DO}$		9.0		6.6		5.8		5.8	ns
		$T_{DOT}$		11.0		7.6		6.2		6.2	ns
<b>Read During Write, Clocking Data into Flip-Flop</b>											
WE setup time before clock K	16x2	$T_{WCK}$	8.0		6.0		5.1		5.1		ns
	32x1	$T_{WCKT}$	9.6		6.8		5.8		5.8		ns
Data setup time before clock K	16x2 32x1	$T_{DCK}$	7.0		5.2		4.4		4.4		ns
		$T_{DCKT}$	8.0		6.2		5.3		5.3		ns
<b>Preliminary</b>											

Note: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.

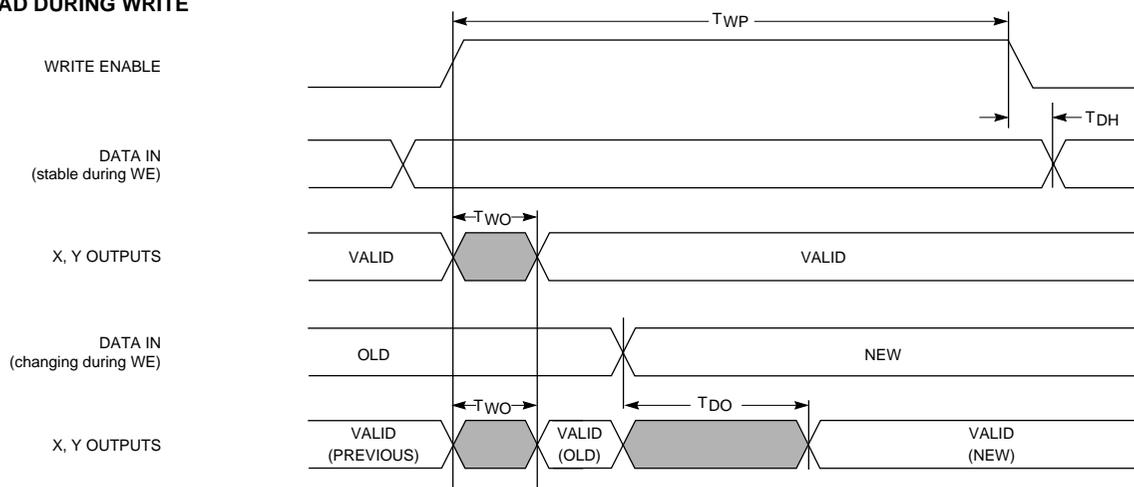
### XC4000E CLB Level-Sensitive RAM Timing Characteristics



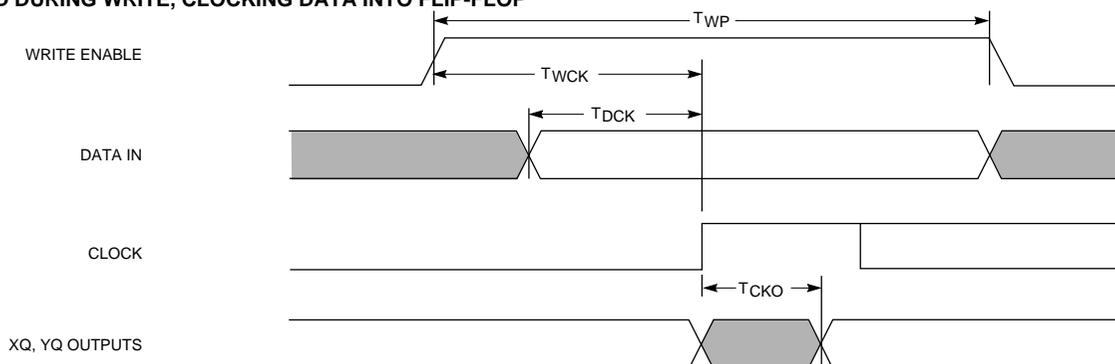
#### READ, CLOCKING DATA INTO FLIP-FLOP



#### READ DURING WRITE



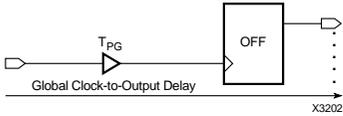
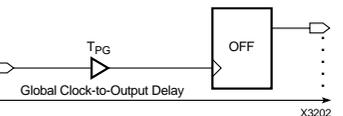
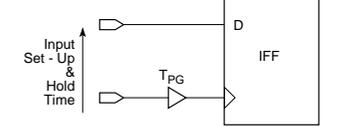
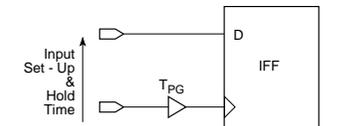
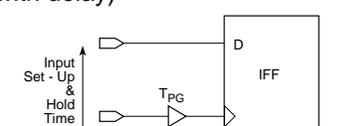
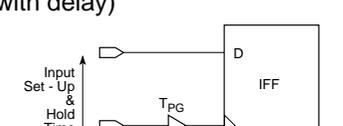
#### READ DURING WRITE, CLOCKING DATA INTO FLIP-FLOP



X2640

## XC4000E Guaranteed Input and Output Parameters (Pin-to-Pin, TTL I/O)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000E devices unless otherwise noted.

Description	Symbol	Device	Speed Grade				Units
			-4	-3	-2	-1	
Global Clock to Output (fast) using OFF	$T_{ICKOF}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	12.5 14.0 14.5 15.0 16.0 16.5 17.0 17.0	10.2 10.7 10.7 10.8 10.9 11.0 11.0 12.6	8.7 9.1 9.1 9.2 9.3 9.4 10.2 10.8	5.8 6.2 6.4 6.6 6.8 7.2 7.4 -	ns ns ns ns ns ns ns ns
	(Max)						
Global Clock to Output (slew-limited) using OFF	$T_{ICKO}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	16.5 18.0 18.5 19.0 20.0 20.5 21.0 21.0	14.0 14.7 14.7 14.8 14.9 15.0 15.1 15.3	11.5 12.0 12.0 12.1 12.2 12.8 12.8 13.0	7.8 8.2 8.4 8.6 8.8 9.2 9.4 -	ns ns ns ns ns ns ns ns
	(Max)						
Input Setup Time, using IFF (no delay)	$T_{PSUF}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	2.5 2.0 1.9 1.4 1.0 0.5 0 0	2.3 1.2 1.0 0.6 0.2 0 0 0	2.3 1.2 1.0 0.6 0.2 0 0 0	1.5 0.8 0.6 0.2 0 0 0 -	ns ns ns ns ns ns ns ns
	(Min)						
Input Hold Time, using IFF (no delay)	$T_{PHF}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	4.0 4.6 5.0 6.0 6.0 7.0 7.5 8.0	4.0 4.5 4.7 5.1 5.5 6.5 6.7 7.0	4.0 4.5 4.7 5.1 5.5 5.5 5.7 5.9	1.5 2.0 2.0 2.5 2.5 3.0 3.5 -	ns ns ns ns ns ns ns ns
	(Min)						
Input Setup Time, using IFF (with delay)	$T_{PSU}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	8.5 8.5 8.5 8.5 8.5 8.5 9.5 9.5	7.0 7.0 7.0 7.0 7.0 7.0 7.0 7.6	6.0 6.0 6.0 6.0 6.0 6.0 6.8 6.8	5.0 5.0 5.0 5.0 5.0 5.0 5.0 -	ns ns ns ns ns ns ns ns
	(Min)						
Input Hold Time, using IFF (with delay)	$T_{PH}$	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 -	ns ns ns ns ns ns ns ns
	(Min)						

OFF = Output Flip-Flop

IFF = Input Flip-Flop or Latch

**Preliminary**

### XC4000E IOB Input Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000E devices unless otherwise noted.

		Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Device	Min	Max	Min	Max	Min	Max	Min	Max		
<b>Propagation Delays (TTL Inputs)</b>												
Pad to I1, I2	T <sub>PID</sub>	All devices		3.0		2.5		2.0		1.4	ns	
Pad to I1, I2 via transparent latch, no delay		T <sub>PLI</sub>	All devices		4.8		3.6		3.6		2.8	ns
with delay	T <sub>PDLI</sub>	XC4003E		10.4		9.3		6.9		6.4	ns	
		XC4005E		10.8		9.6		7.4		6.5	ns	
		XC4006E		10.8		10.2		8.1		6.9	ns	
		XC4008E		10.8		10.6		8.2		7.0	ns	
		XC4010E		11.0		10.8		8.3		7.3	ns	
		XC4013E		11.4		11.2		9.8		8.4	ns	
		XC4020E		13.8		12.4		11.5		9.0	ns	
		XC4025E		13.8		13.7		12.4		–	ns	
<b>Propagation Delays (CMOS Inputs)</b>												
Pad to I1, I2	T <sub>PIDC</sub>	All devices		5.5		4.1		3.7		1.9	ns	
Pad to I1, I2 via transparent latch, no delay	T <sub>PLIC</sub>	All devices		8.8		6.8		6.2		3.3	ns	
with delay	T <sub>PDLIC</sub>	XC4003E		16.5		12.4		11.0		6.9	ns	
		XC4005E		16.5		13.2		11.9		7.0	ns	
		XC4006E		16.8		13.4		12.1		7.4	ns	
		XC4008E		17.3		13.8		12.4		7.4	ns	
		XC4010E		17.5		14.0		12.6		7.8	ns	
		XC4013E		18.0		14.4		13.0		9.0	ns	
		XC4020E		20.8		15.6		14.0		9.5	ns	
		XC4025E		20.8		15.6		14.0		–	ns	
<b>Propagation Delays</b>												
Clock (IK) to I1, I2 (flip-flop)	T <sub>IKRI</sub>	All devices		5.6		2.8		2.8		2.7	ns	
Clock (IK) to I1, I2 (latch enable, active Low)	T <sub>IKLI</sub>	All devices		6.2		4.0		3.9		3.2	ns	
<b>Hold Times (Note 1)</b>												
Pad to Clock (IK), no delay	T <sub>IKPI</sub>	All devices	0		0		0		0		ns	
with delay	T <sub>IKPID</sub>	All devices	0		0		0		0		ns	
Clock Enable (EC) to Clock (IK), no delay	T <sub>IKEC</sub>	All devices	1.5		1.5		0.9		0		ns	
with delay	T <sub>IKECD</sub>	All devices	0		0		0		0		ns	

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- Note 1: Input pad setup and hold times are specified with respect to the internal clock (IK). For setup and hold times with respect to the clock input pin, see the pin-to-pin parameters in the Guaranteed Input and Output Parameters table.
- Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

## XC4000E IOB Input Switching Characteristic Guidelines (continued)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

		Speed Grade		-4		-3		-2		-1		Units
Description		Symbol	Device	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Setup Times (TTL Inputs)</b>												
Pad to Clock (IK), no delay with delay	$T_{PICK}$	All devices	4.0		2.6		2.0		1.5		ns	
		XC4003E	10.9		8.2		6.0		4.8		ns	
	$T_{PICKD}$	XC4005E	10.9		8.7		6.1		5.1		ns	
		XC4006E	10.9		9.2		6.2		5.8		ns	
		XC4008E	11.1		9.6		6.3		5.8		ns	
		XC4010E	11.3		9.8		6.4		6.0		ns	
		XC4013E	11.8		10.2		7.9		7.6		ns	
		XC4020E	14.0		11.4		9.4		8.2		ns	
		XC4025E	14.0		11.4		10.0		–		ns	
<b>Setup Time (CMOS Inputs)</b>												
Pad to Clock (IK), no delay with delay	$T_{PICKC}$	All devices	6.0		3.3		2.4		2.4		ns	
		XC4003E	12.0		8.8		6.9		5.3		ns	
	$T_{PICKDC}$	XC4005E	12.0		9.7		8.0		5.6		ns	
		XC4006E	12.3		9.9		8.1		6.3		ns	
		XC4008E	12.8		10.3		8.2		6.3		ns	
		XC4010E	13.0		10.5		8.3		6.5		ns	
		XC4013E	13.5		10.9		10.0		7.9		ns	
		XC4020E	16.0		12.1		12.1		8.1		ns	
		XC4025E	16.0		12.1		12.1		–		ns	
<b>(TTL or CMOS)</b>												
Clock Enable (EC) to Clock (IK), no delay with delay	$T_{EICK}$	All devices	3.5		2.5		2.1		1.5		ns	
		XC4003E	10.4		8.1		4.3		4.3		ns	
	$T_{EICKD}$	XC4005E	10.4		8.5		5.6		5.0		ns	
		XC4006E	10.4		9.1		6.7		6.0		ns	
		XC4008E	10.4		9.5		6.9		6.0		ns	
		XC4010E	10.7		9.7		7.1		6.5		ns	
		XC4013E	11.1		10.1		9.0		8.0		ns	
		XC4020E	14.0		11.3		10.6		9.0		ns	
		XC4025E	14.0		11.3		11.0		–		ns	
<b>Global Set/Reset (Note 3)</b>												
Delay from GSR net through Q to I1, I2	$T_{RRI}$			12.0		7.8		6.8		6.8	ns	
	$T_{MRW}$		13.0		11.5		11.5		10.0		ns	
GSR width	$T_{MRI}$										ns	
GSR inactive to first active Clock (IK) edge											ns	

Preliminary

- Note 1: Input pad setup and hold times are specified with respect to the internal clock (IK). For setup and hold times with respect to the clock input pin, see the pin-to-pin parameters in the Guaranteed Input and Output Parameters table.
- Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.
- Note 3: Timing is based on the XC4005E. For other devices see the XACT timing calculator.

### XC4000E IOB Output Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Propagation Delays (TTL Output Levels)</b>										
Clock (OK) to Pad, fast	T <sub>OKPOF</sub>		7.5		6.5		4.5		3.0	ns
slew-rate limited	T <sub>OKPOS</sub>		11.5		9.5		7.0		5.0	ns
Output (O) to Pad, fast	T <sub>OPF</sub>		8.0		5.5		4.8		3.2	ns
slew-rate limited	T <sub>OPS</sub>		12.0		8.5		7.3		5.2	ns
3-state to Pad hi-Z (slew-rate independent)	T <sub>TSHZ</sub>		5.0		4.2		3.8		3.0	ns
3-state to Pad active and valid, fast	T <sub>TSONF</sub>		9.7		8.1		7.3		6.8	ns
slew-rate limited	T <sub>TSONS</sub>		13.7		11.1		9.8		8.8	ns
<b>Propagation Delays (CMOS Output Levels)</b>										
Clock (OK) to Pad, fast	T <sub>OKPOFC</sub>		9.5		7.8		7.0		4.0	ns
slew-rate limited	T <sub>OKPOSC</sub>		13.5		11.6		10.4		7.0	ns
Output (O) to Pad, fast	T <sub>OPFC</sub>		10.0		9.7		8.7		4.0	ns
slew-rate limited	T <sub>OPSC</sub>		14.0		13.4		12.1		6.0	ns
3-state to Pad hi-Z (slew-rate independent)	T <sub>TSHZC</sub>		5.2		4.3		3.9		3.9	ns
3-state to Pad active and valid, fast	T <sub>TSONFC</sub>		9.1		7.6		6.8		6.8	ns
slew-rate limited	T <sub>TSONSC</sub>		13.1		11.4		10.2		8.8	ns

Preliminary

- Note 1: Output timing is measured at pin threshold, with 50pF external capacitive loads (incl. test fixture). Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times. For the effect of capacitive loads on ground bounce, see the "Additional XC4000 Data" section of the Programmable Logic Data Book.
- Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

## XC4000E IOB Output Switching Characteristic Guidelines (continued)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation netlist. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). For Propagation Delays, slew-rate = fast unless otherwise noted. Values apply to all XC4000E devices unless otherwise noted.

Speed Grade		-4		-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Setup and Hold</b>										
Output (O) to clock (OK) setup time	$T_{OOK}$	5.0		4.6		3.8		2.3		ns
Output (O) to clock (OK) hold time	$T_{OKO}$	0		0		0		0		ns
Clock Enable (EC) to clock (OK) setup	$T_{ECOK}$	4.8		3.5		2.7		2.0		ns
Clock Enable (EC) to clock (OK) hold	$T_{OKEC}$	1.2		1.2		0.5		0		ns
<b>Clock</b>										
Clock High	$T_{CH}$	4.5		4.0		4.0			3.0	ns
Clock Low	$T_{CL}$	4.5		4.0		4.0			3.0	ns
<b>Global Set/Reset (Note 3)</b>										
Delay from GSR net to Pad	$T_{RPO}$		15.0		11.8		8.7		7.0	ns
GSR width	$T_{MRW}$	13.0		11.5		11.5				ns
GSR inactive to first active clock (OK) edge	$T_{MRO}$									ns

**Preliminary**

- Note 1: Output timing is measured at pin threshold, with 50pF external capacitive loads (incl. test fixture). Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times. For the effect of capacitive loads on ground bounce, see the "Additional XC4000 Data" section of the Programmable Logic Data Book.
- Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.
- Note 3: Timing is based on the XC4005E. For other devices see the XACT timing calculator.

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